

A Semidefinite Relaxation Scheme for Multivariate Quartic Polynomial Optimization With Quadratic Constraints

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In this work we consider the optimization of a multivariate fourth order (quartic) polynomial under quadratic constraints. The problem can take either the maximization form

$$\begin{array}{ll} \text{maximize} & f(x) = \sum_{1 \leq i, j, k, \ell \leq n} a_{ijkl} x_i x_j x_k x_\ell \\ \text{subject to} & x^T A_i x \leq 1, i = 1, \dots, m, \end{array} \quad (1)$$

or the minimization form

$$\begin{array}{ll} \text{minimize} & f(x) = \sum_{1 \leq i, j, k, \ell \leq n} a_{ijkl} x_i x_j x_k x_\ell \\ \text{subject to} & x^T A_i x \geq 1, i = 1, \dots, m, \end{array} \quad (2)$$

where A_i 's are positive semidefinite matrices in $\mathbb{R}^{n \times n}$, $i = 1, \dots, m$. Let f_{\max} and f_{\min} denote the optimal values of (1) and (2) respectively. Throughout, we assume $f_{\min} \geq 0$.

Quartic optimization problems arise in various engineering applications such as independent component analysis [2], blind channel equalization in digital communication [4] and sensor localization [9]. From the complexity standpoint, the nonconvex quartic polynomial optimization problems (1)–(2) are NP-hard. This motivates us to consider polynomial time relaxation procedures that can deliver provably high quality approximate solutions.

As a special case of the general polynomial optimization problem, the quartic optimization problems (1)–(2) can be relaxed using the standard SOS technique of semidefinite programming relaxation. Specifically, by representing each nonnegative polynomial as a sum of squares of some

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other polynomials (SOS) [3] of a given degree, it is possible to relax each polynomial inequality as a convex linear matrix inequality (LMI). In this way, as the polynomial degree in SOS representation increases, the nonconvex quartic optimization problems (1)–(2) can be approximated by a hierarchy of semidefinite programs (SDP) with increasing size. While this SOS relaxation scheme can achieve, at least theoretically, asymptotic global optimality, the size of the resulting SDPs in the hierarchy grows exponentially fast. This presents great computational challenges in practice, so much so that it severely limits the application scope of the SOS relaxation approach. Indeed, the most effective use of SDP relaxation so far has been for the quadratic optimization problems whereby only the first level relaxation in the SOS hierarchy is used. Even though such SDP relaxation does not always provide a tight approximation in general, it does lead to provably high quality approximate solution for certain type of quadratic optimization problems. The latter includes various graph problems such as the Max-Cut problem [1] as well as some homogeneous nonconvex quadratic optimization problems [5–8, 10].

In this work we present a general semidefinite relaxation scheme for n -variate quartic polynomial optimization under homogeneous quadratic constraints. Unlike the existing sum-of-squares (SOS) approach which relaxes the quartic optimization problems to a sequence of (typically large) linear semidefinite programs (SDP) over $\mathbb{R}^{n^2 \times n^2}$, our relaxation scheme leads to a (possibly nonconvex) quadratic optimization problem with linear constraints over the semidefinite matrix cone in $\mathbb{R}^{n \times n}$. It is shown that each α -approximate solution of the relaxed quadratic SDP can be used to generate in randomized polynomial time an $O(\alpha/\ln^2(mn))$ -approximate solution for the original quartic optimization problem, where m is the number of constraints in the problem. In the case where only one quadratic constraint is present, we provide a polynomial time $\Omega((n \ln^2 n)^{-1})$ -approximation algorithm for the quartic maximization problem and a polynomial time $O(n^2)$ -approximation algorithm for the quartic minimization problem.

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