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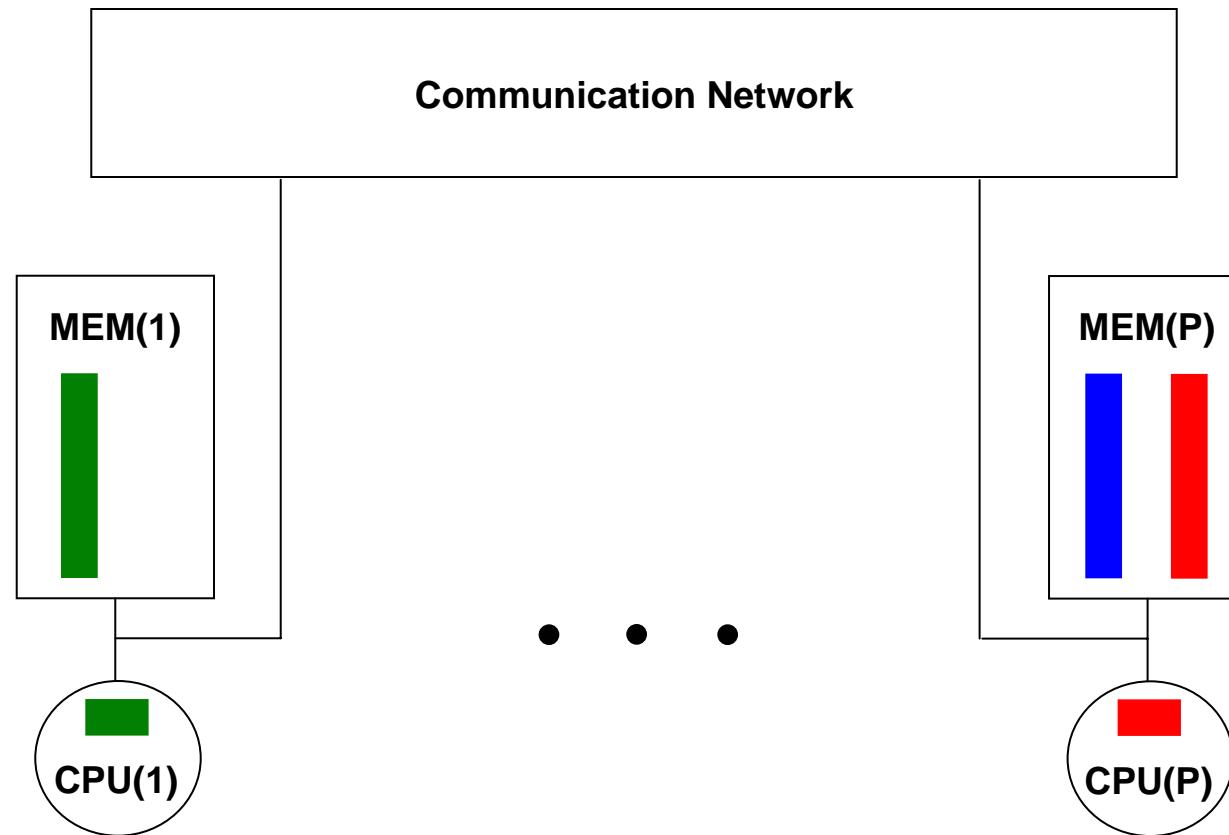
Parallel-Server Stochastic Systems with Dynamic Affinity Scheduling and Load Balancing

Mark S. Squillante*
Mathematical Sciences Department
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* Based mostly on joint work with R. Nelson

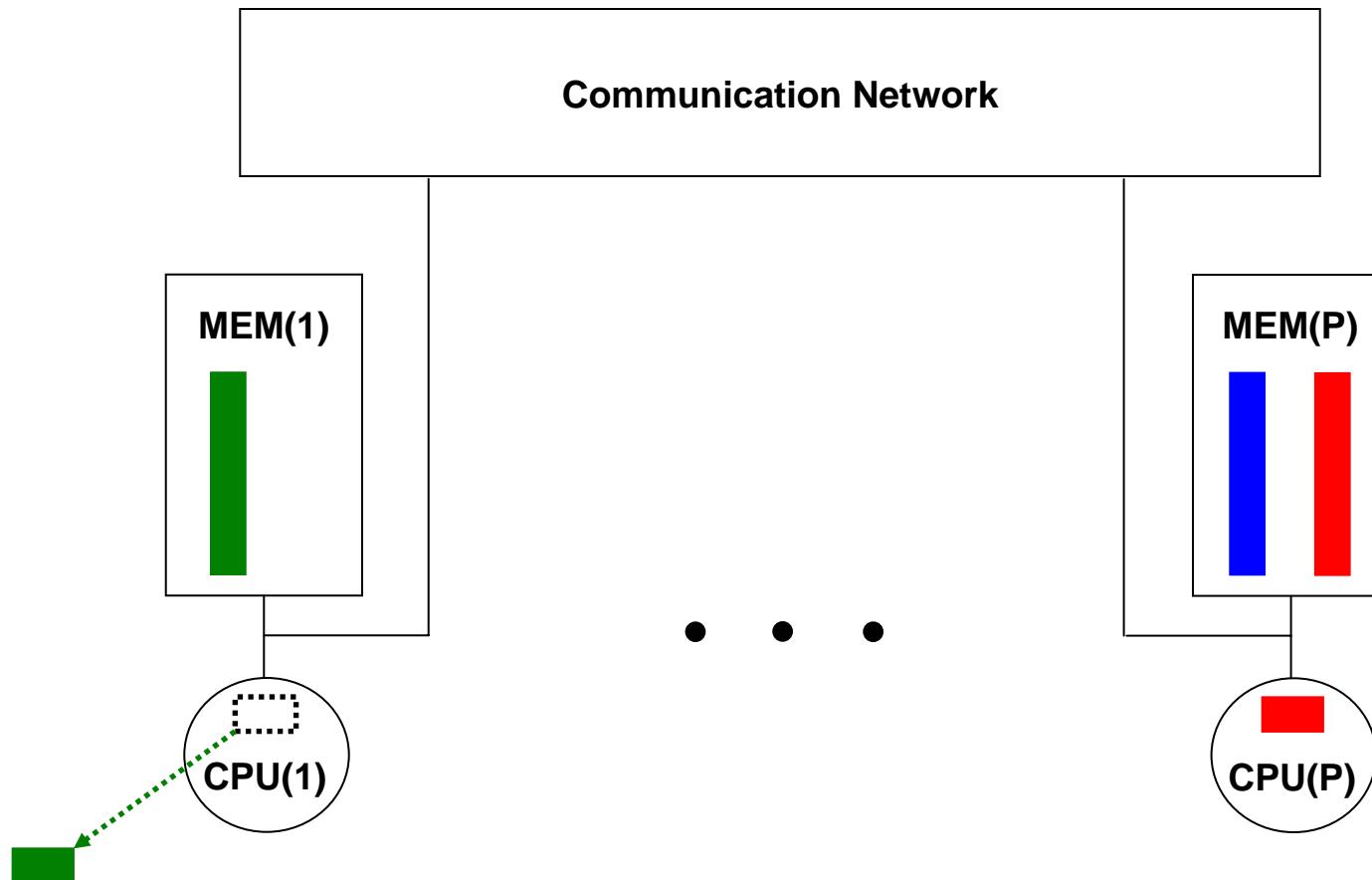
Problem Motivation

Parallel Computing Example



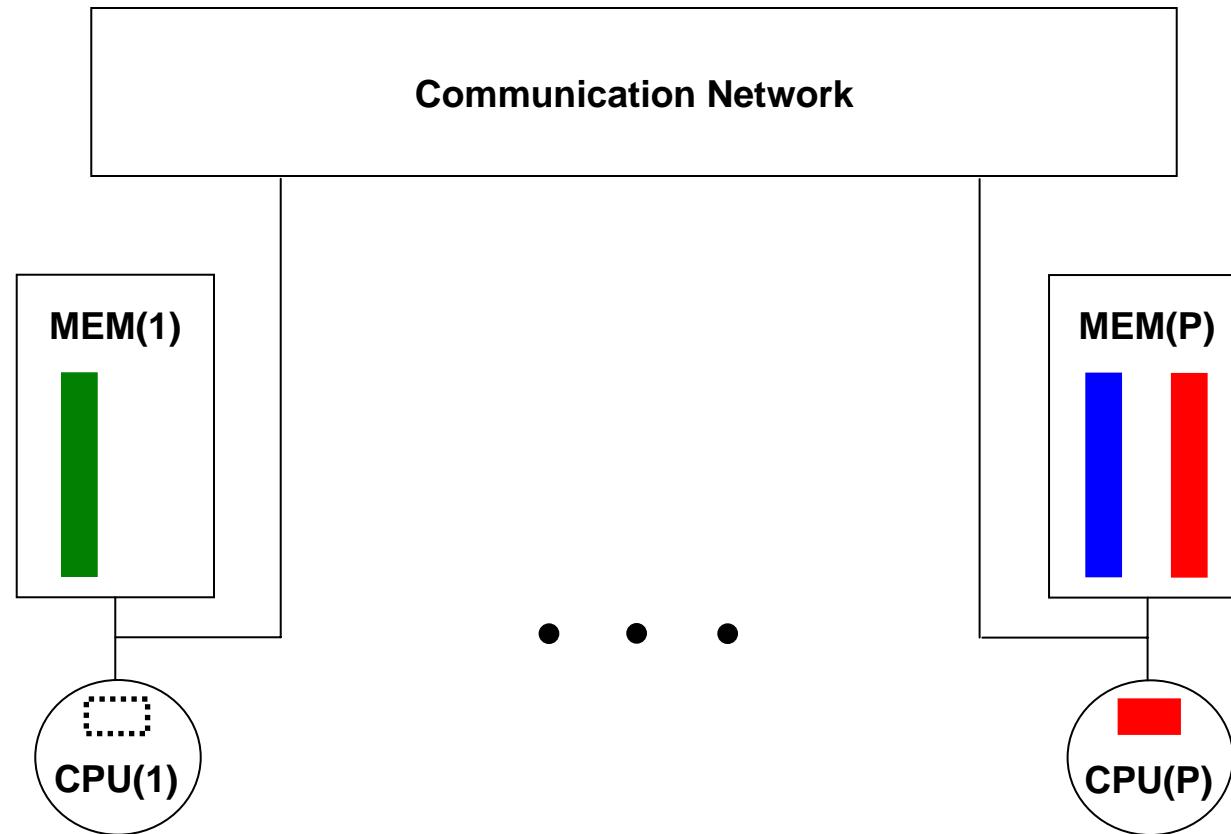
Problem Motivation

Parallel Computing Example



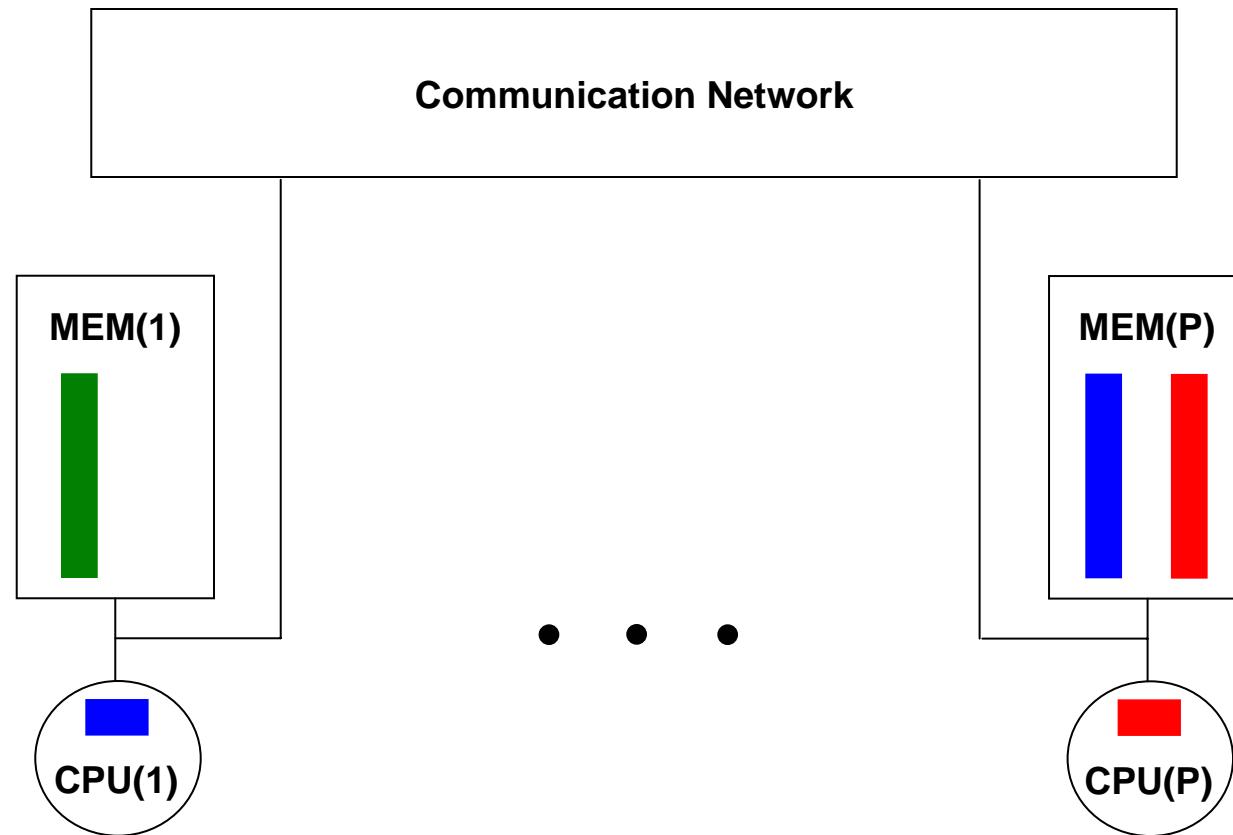
Problem Motivation

Dynamic Scheduling Tradeoff: Should we leave CPU(1) idle?



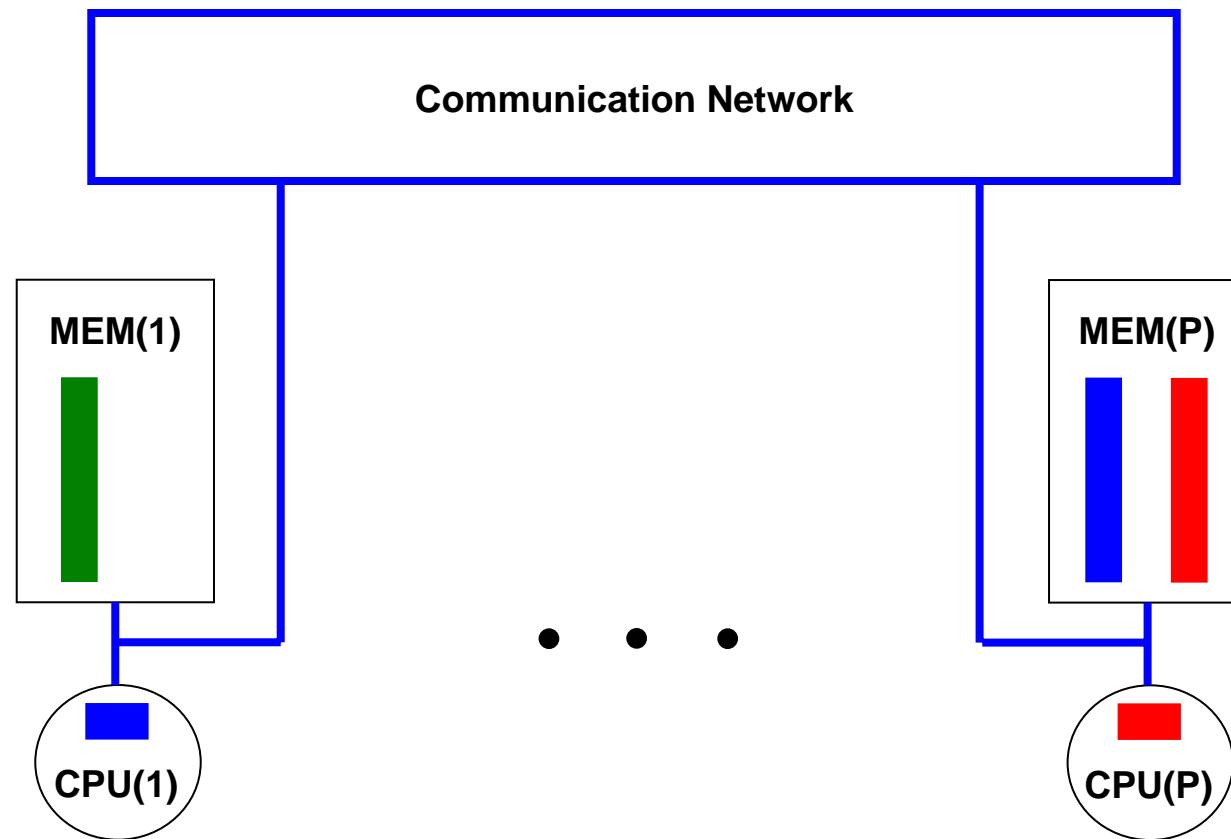
Problem Motivation

Dynamic Scheduling Tradeoff: Or serve Blue-Task at CPU(1)?



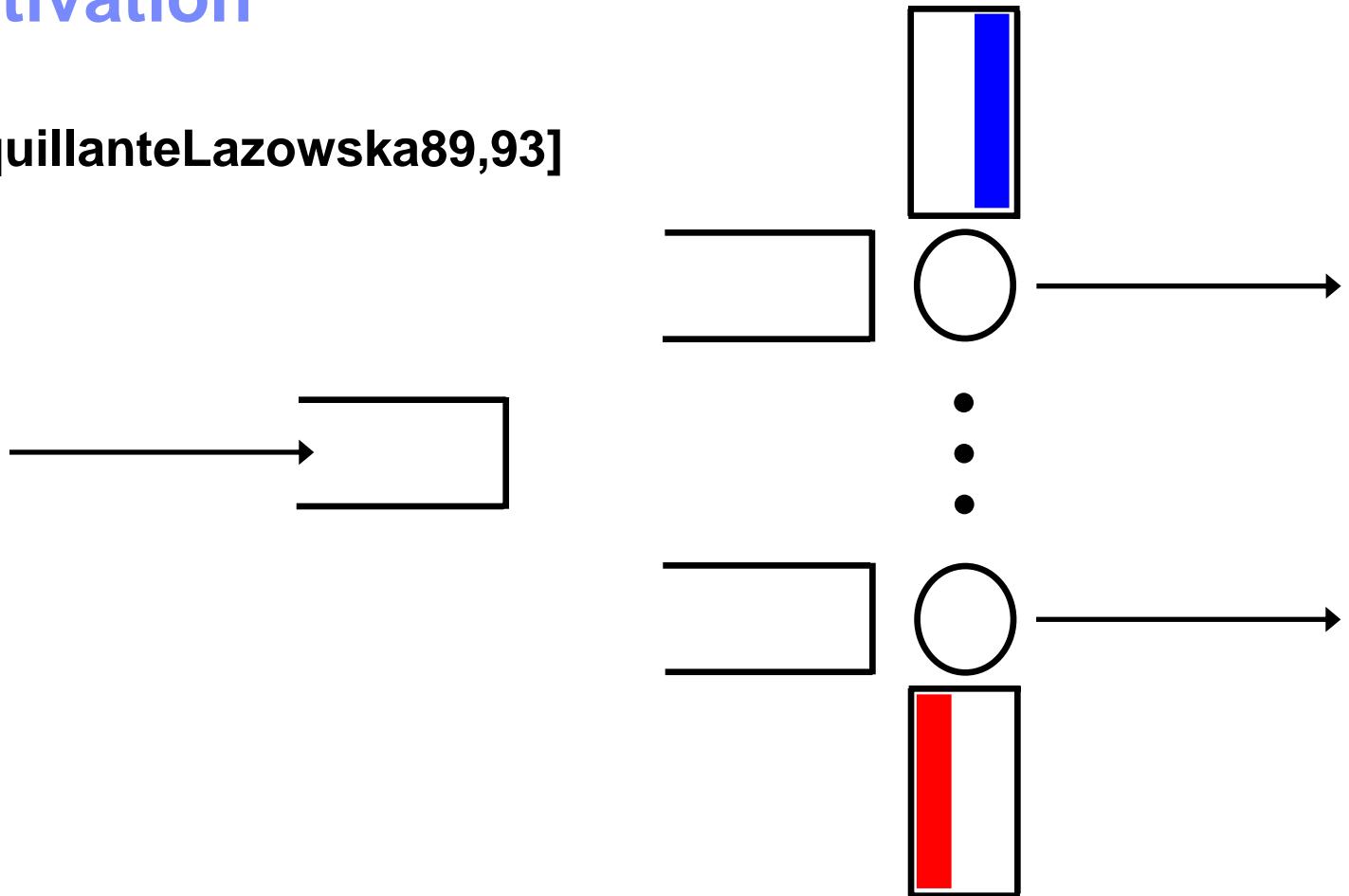
Problem Motivation

Dynamic Scheduling Tradeoff: But larger **Blue-Task service time**



Problem Motivation

Cache Affinity [SquillanteLazowska89,93]



Key Points of Fundamental Tradeoff

- Customers can be served on any server of a parallel-server queueing system
- Each customer is served most efficiently on one of the servers
- Load imbalance among queues occurs due to stochastic properties of system

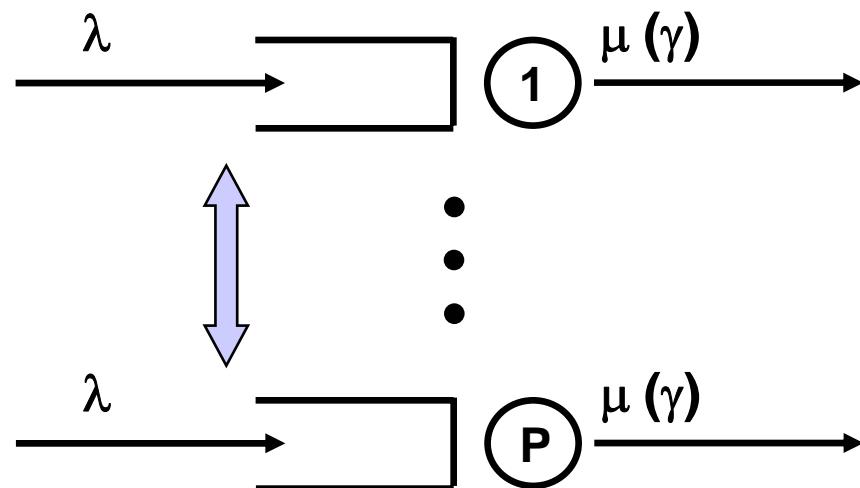


General Overview

- Optimal Scheduling Policy
 - Fluid control problem: $c\mu$ -type scheduling policy
 - Brownian control problem: dynamic threshold-type scheduling policy
 - Optimal threshold settings for dynamic scheduling policy depend upon stochastic properties and traffic intensity of system
- Analysis of Dynamic Threshold Scheduling
 - Consider generalized threshold scheduling policy
 - Matrix-analytic analysis and fix-point solution, asymptotically exact
 - Numerical experiments
 - Optimal settings of dynamic scheduling policy thresholds
- Stochastic Derivative-Free Optimization

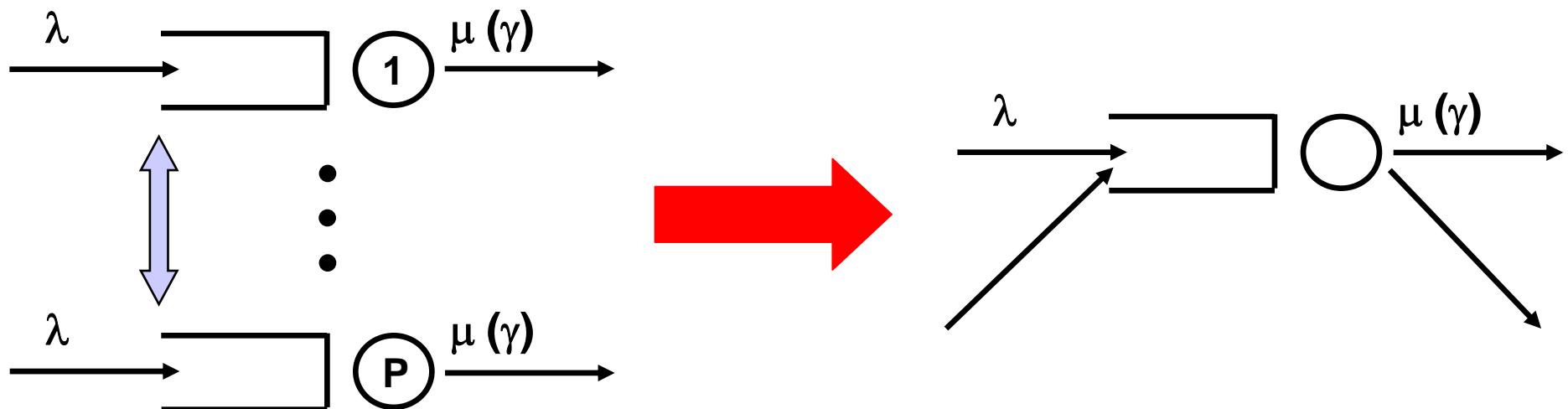
Scheduling Policy

$$\begin{aligned}\beta &\equiv (T_r^\ell, T_s^\ell, T_r^u, T_s^u), \quad 0 \leq \{T_r^\ell, T_s^\ell\} \leq \{T_r^u, T_s^u\} < \infty \\ K &\equiv \max\{T_r^\ell, T_s^\ell\}, \quad \hat{T} \equiv \max\{T_r^u, T_s^u\}\end{aligned}$$



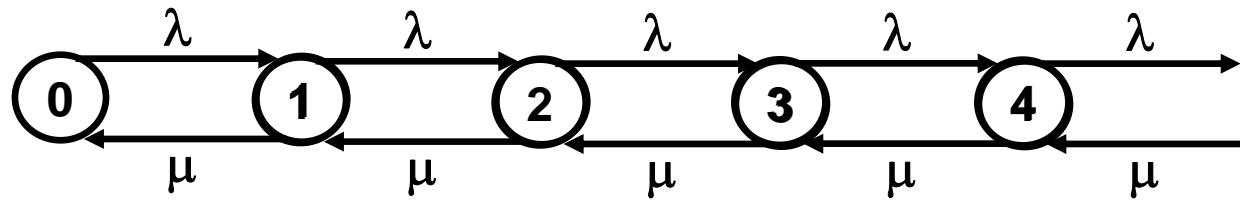
Scheduling Model

$$\begin{aligned}\beta &\equiv (T_r^\ell, T_s^\ell, T_r^u, T_s^u), \quad 0 \leq \{T_r^\ell, T_s^\ell\} \leq \{T_r^u, T_s^u\} < \infty \\ K &\equiv \max\{T_r^\ell, T_s^\ell\}, \quad \hat{T} \equiv \max\{T_r^u, T_s^u\}\end{aligned}$$



Background on Matrix-Analytic Methods

BD process

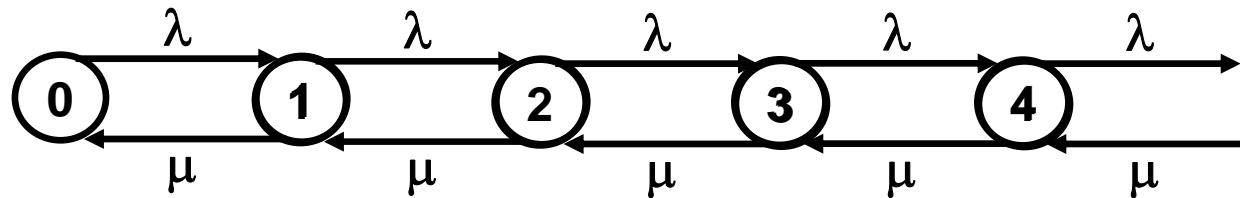


Define $\pi_n \equiv \lim_{t \rightarrow \infty} P[N(t) = n]$, $\pi \equiv (\pi_0, \pi_1, \pi_2, \dots)$

$$Q = \begin{bmatrix} -\lambda & \lambda & 0 & 0 & 0 & \dots \\ \mu & -(\lambda + \mu) & \lambda & 0 & 0 & \dots \\ 0 & \mu & -(\lambda + \mu) & \lambda & 0 & \dots \\ 0 & 0 & \mu & -(\lambda + \mu) & \lambda & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

Background on Matrix-Analytic Methods

BD process



Then solution of $\pi Q = 0$ and $\pi e = 1$ given by

$$\pi_i = \pi_0 \rho^i$$

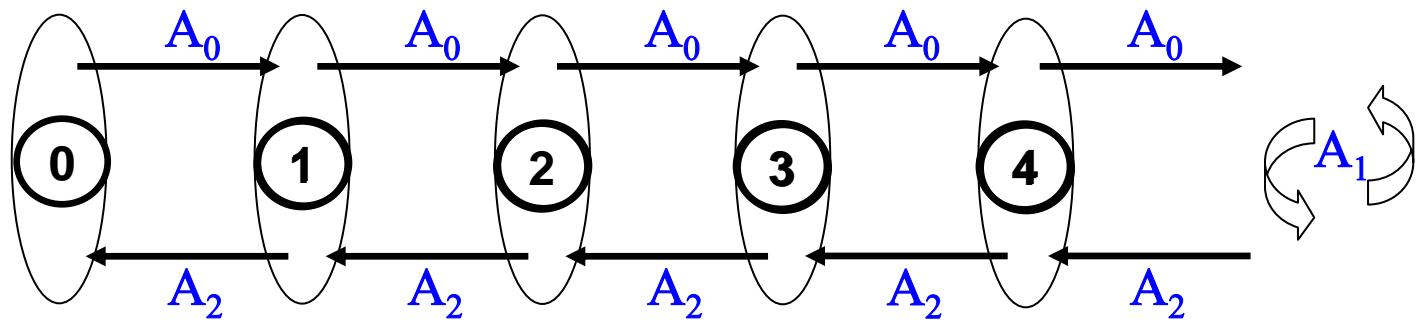
where

$$0 = \lambda - \rho(\lambda + \mu) + \rho^2\mu, \quad \rho < 1 \Rightarrow \rho = \lambda/\mu < 1$$

$$\pi e = 1 \Rightarrow \pi_0 \sum_{i=0}^{\infty} \rho^i = 1 \Rightarrow \pi_0 = 1 - \rho$$

Background on Matrix-Analytic Methods

QBD process

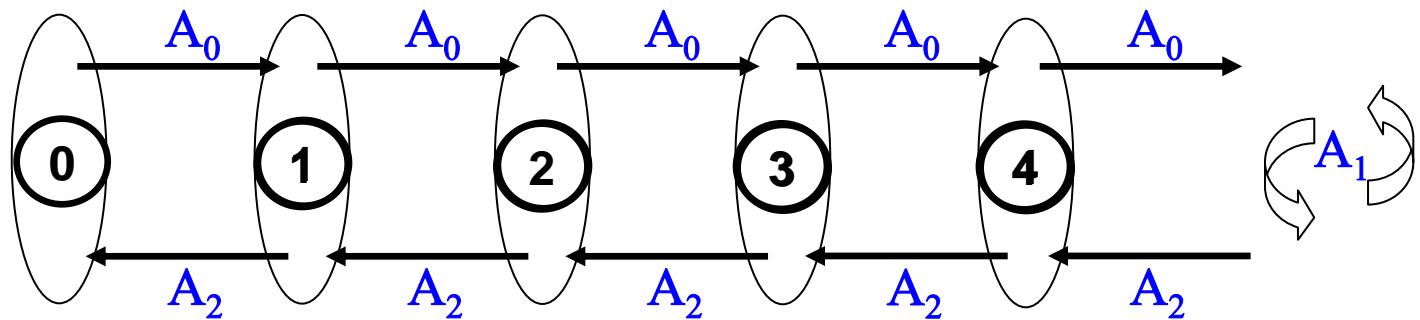


Define $\pi_n \equiv (\pi_{n,1}, \dots, \pi_{n,m})$, $\pi \equiv (\pi_0, \pi_1, \pi_2, \dots)$

$$Q = \begin{bmatrix} B_0 & A_0 & 0 & 0 & 0 & \dots \\ A_2 & A_1 & A_0 & 0 & 0 & \dots \\ 0 & A_2 & A_1 & A_0 & 0 & \dots \\ 0 & 0 & A_2 & A_1 & A_0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

Background on Matrix-Analytic Methods

QBD process



Then solution of $\pi Q = 0$ and $\pi e = 1$ given by

$$\pi_i = \pi_0 R^i$$

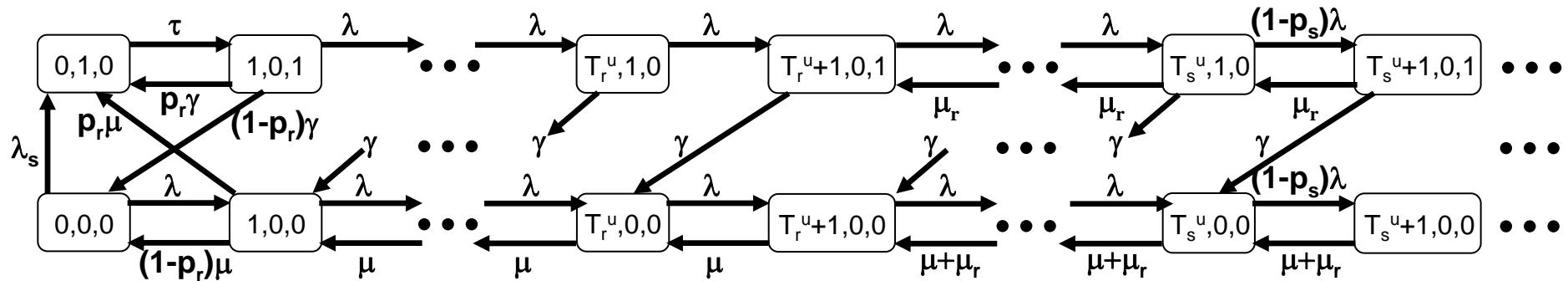
where

$$0 = A_0 + RA_1 + R^2A_2, \quad \text{sp}(R) < 1$$

$$0 = \pi_0(B_0 + RA_2), \quad \pi_0(I - R)^{-1}e = 1$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$

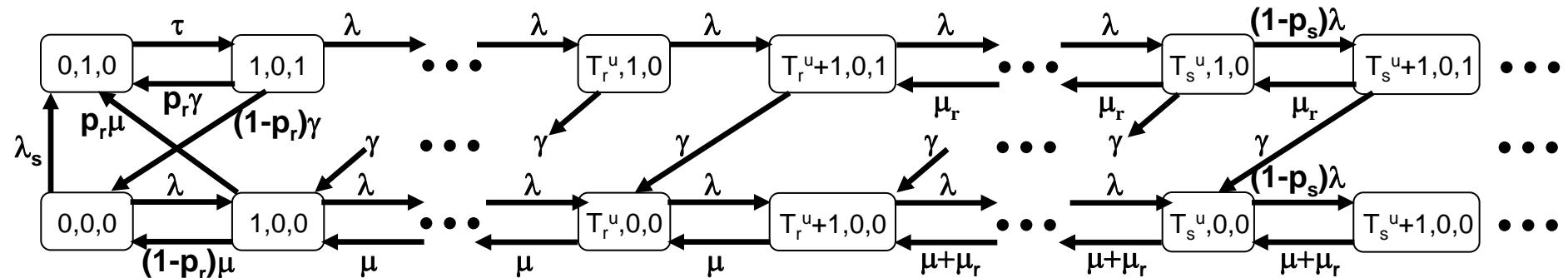


State Vector (i, j, v):

- i : total number of customers waiting or receiving service at the server of interest
 - j : number of customers in the process of being migrated to the server of interest
 - v : K -bit binary vector denoting customer type of up to the first K customers at the server

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$

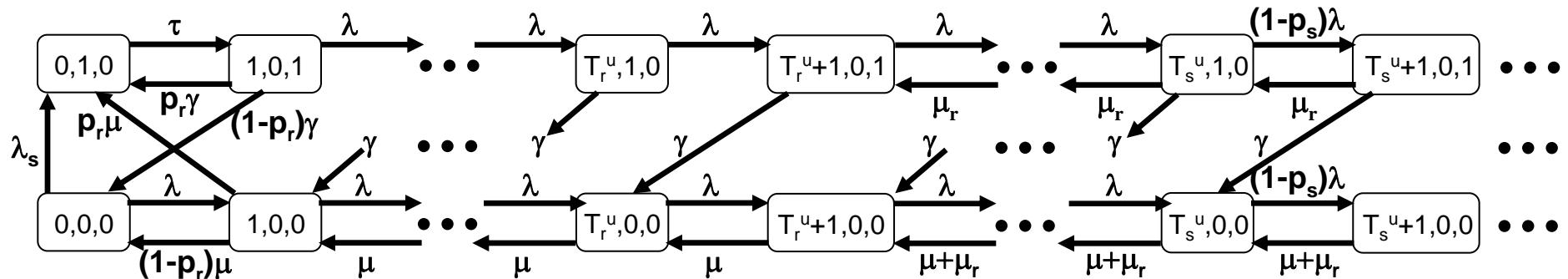


Define $\pi_0 \equiv (\pi_{0,0,0}, \pi_{0,1,0})$, $\pi_n \equiv (\pi_{n,0,0}, \pi_{n,0,1})$, $n > 0$

$$Q = \begin{bmatrix} B_{00} & B_{01} & 0 & 0 & 0 & \dots \\ B_{10} & B_{11} & A_0 & 0 & 0 & \dots \\ 0 & A_2 & A_1 & A_0 & 0 & \dots \\ 0 & 0 & A_2 & A_1 & A_0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



Then solution of $\pi Q = 0$, $\pi e = 1$ is given by

$$\pi_{\hat{T}+k} = \pi_{\hat{T}} R^k, \quad k \geq 0$$

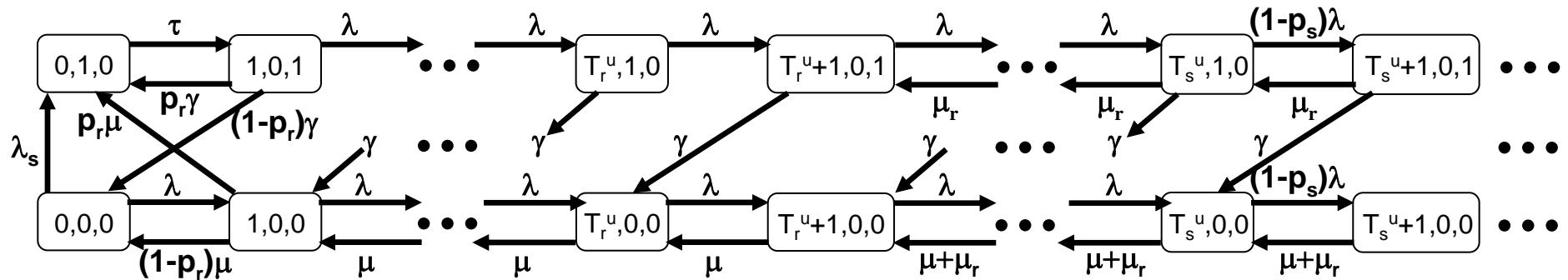
$$0 = A_0 + RA_1 + R^2A_2, \quad \text{sp}(R) < 1$$

$$0 = (\pi_0, \pi_1, \dots, \pi_{\hat{T}}) \begin{bmatrix} B_{00} & B_{01} \\ B_{10} & B_{11} + RA_2 \end{bmatrix}$$

$$1 = (\pi_0, \pi_1, \dots, \pi_{\hat{T}-1})e + \pi_{\hat{T}}(I - R)^{-1}e$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



Probabilistic Interpretation of \mathbf{R} :

$$r_{00} = \frac{\lambda(1 - p_s)}{\mu + \mu_r},$$

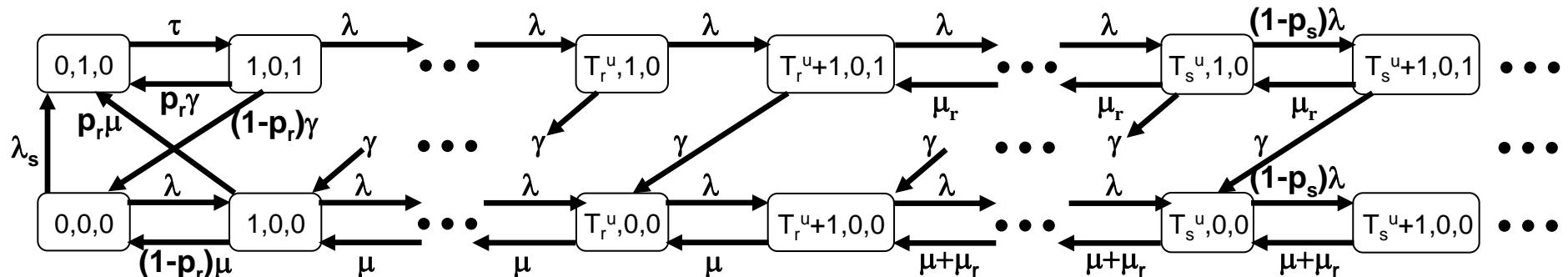
$$r_{01} = 0$$

$$r_{11} = \frac{\lambda(1 - p_s) + \gamma + \mu_r - ((\lambda(1 - p_s) + \gamma + \mu_r)^2 - 4\lambda(1 - p_s)\mu_r)^{1/2}}{2\mu_r}$$

$$r_{10} = \frac{r_{11}^2 \gamma}{(\mu + \mu_r)(1 - r_{11})}$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



Let I, J, V be generic r.v.s of the process

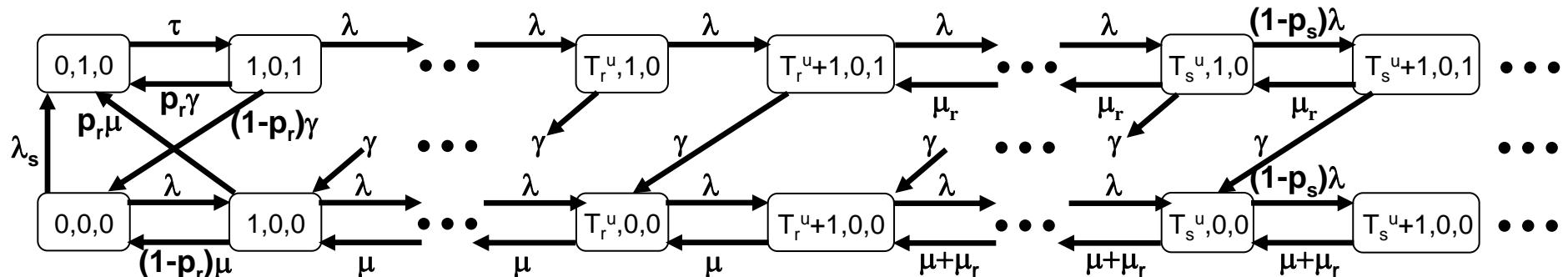
$$\begin{aligned} p_s &= \mathbb{P} [\text{Find Queue with } I + J < T_s^\ell \text{ in } \leq L_p \text{ Random Probes}] \\ &= 1 - (1 - \mathbb{P} [I + J < T_s^\ell])^{L_p} \end{aligned}$$

Equating inflow and outflow of SI migrated customers:

$$\lambda_s \mathbb{P} [I + J < T_s^\ell] = \lambda p_s \mathbb{P} [I \geq T_s^u]$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



Let I, J, \underline{V} be generic r.v.s of the process

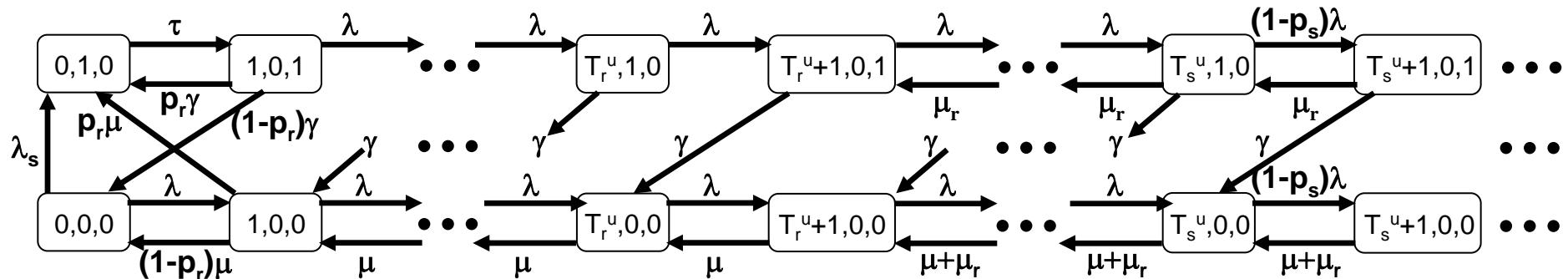
$$\begin{aligned} p_r &= \text{P [Find Queue with } I > T_r^u \text{ in } \leq L_p \text{ Random Probes]} \\ &= 1 - (1 - \text{P}[I > T_r^u])^{L_p} \end{aligned}$$

Equating inflow and outflow of RI migrated customers:

$$\begin{aligned} \mu_r \text{P} [I > T_r^u] &= \mu p_r \text{P} [I + J \leq T_r^\ell, I > 0, v_1 = 0] + \\ &\quad \gamma p_r \text{P} [I + J \leq T_r^\ell, I > 0, v_1 = 1] \end{aligned}$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$

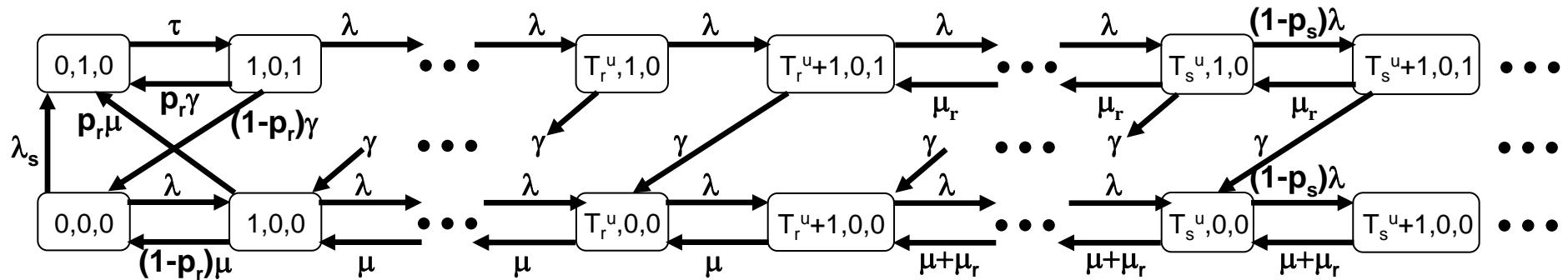


Final Solution Obtained via Fix-Point Iteration

1. Initialize $(\mathbf{p}_s, \lambda_s, \mathbf{p}_r, \mu_r)$
 2. Compute stationary probability vector in terms of $(\mathbf{p}_s, \lambda_s, \mathbf{p}_r, \mu_r)$
 3. Compute new values of $(\mathbf{p}_s, \lambda_s, \mathbf{p}_r, \mu_r)$ in terms of stationary vector
 4. Goto 2 until differences between iteration values are arbitrarily small

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



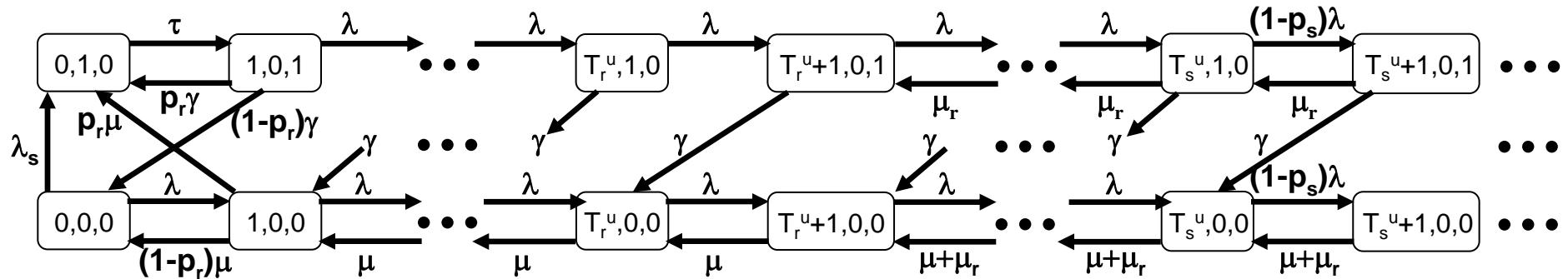
Stability criterion: $\text{sp}(\mathbf{R}) = r_{00} < 1$, $\mathbf{A} \equiv \mathbf{A}_0 + \mathbf{A}_1 + \mathbf{A}_2$ reducible

$$\mathbb{E} [\mathcal{T}] = \lambda^{-1} \left\{ \sum_{k=1}^{\hat{T}-1} k \pi_k \mathbf{e} + \hat{T} \pi_{\hat{T}} (\mathbf{I} - \mathbf{R})^{-1} \mathbf{e} + \pi_{\hat{T}} (\mathbf{I} - \mathbf{R})^{-2} \mathbf{R} \mathbf{e} \right\}$$

$$p_{mt} = (\boldsymbol{\pi}_1, \dots, \boldsymbol{\pi}_K) \nu + \sum_{k=K+1}^{\hat{T}-1} \boldsymbol{\pi}_k \nu' + \boldsymbol{\pi}_{\hat{T}} (\mathbf{I} - \mathbf{R})^{-1} \nu'$$

Mathematical Analysis

$$T_r^\ell = T_s^\ell = K = 1, \quad T_r^u < T_s^u = \hat{T}, \quad \exp(\lambda), \exp(\mu), \exp(\gamma)$$



Tail asymptotics:

$$\mathbb{P}[Q > x] = \frac{\pi_{\hat{T}}^{\text{v}}}{1 - \eta} \eta^x + o(\eta^x), \quad \text{as } x \rightarrow \infty,$$

$$\mathbb{P}[Q > x] \sim \frac{\pi_{\hat{T}}^{\text{v}}}{1 - \eta} \eta^x, \quad \text{as } x \rightarrow \infty,$$

where u and v are the left and right eigenvectors corresponding to $\eta = r_{00}$ normalized by $\text{u}\text{e} = 1$ and $\text{u}\text{v} = 1$



Mathematical Analysis

General K, Pure Sender-Initiated Policy

Probabilistic Interpretation of R:

$$\begin{aligned} r_{00} &= \lambda(1 - p_s)/\mu \\ r_{nm} &= 0, \quad 0 \leq n < m \leq 2^K - 1 \quad (\text{lower triangular}) \\ r_{nn}^0 &= \Phi(n), \quad 1 \leq n \leq 2^K - 1 \\ r_{nm}^0 &= C_k \Phi(n)^{k+1} \Psi(n)^k, \quad (*) \\ &\quad n > m > 0 \text{ s.t. } b_m = \mathcal{D}_k(b_n), \quad 1 \leq k < K \\ r_{n0} &= \frac{\gamma \sum_{k=1}^n r_{nk} r_{k1} + \mu \sum_{k=1}^{n-1} r_{nk} r_{k0}}{\lambda(1 - p_s) + \mu(1 - r_{00} - r_{nn})}, \\ &\quad 1 \leq n \leq 2^K - 1 \end{aligned}$$



Mathematical Analysis

General K

Departure Transitions from State (i, j, \underline{v}) , $i > 0$, $j \leq (K - i)^+$

To State	Rate
$(i - 1, j, \mathcal{D}_1(\underline{v}))$, $i + j \leq T_r^\ell \leq K$	$(1 - p_r)e(\underline{v})$
$(i - 1, j + 1, \mathcal{D}_1(\underline{v}))$, $i + j \leq T_r^\ell \leq K$	$p_r e(\underline{v})$
$(i - 1, j, \mathcal{D}_1(\underline{v}))$, $T_r^\ell < i + j \leq T_r^u$	$e(\underline{v})$
$(i - 1, j, \underline{v})$, $\underline{v} \neq 0$, $i > T_r^u$	μ_r
$(i - 1, j, \mathcal{D}_1(\underline{v}))$, $\underline{v} \neq 0$, $i > T_r^u$	$e(\underline{v})$
$(i - 1, j, \mathcal{D}_1(\underline{v}))$, $\underline{v} = 0$, $i > T_r^u$	$e(\underline{v}) + \mu_r$

$$\mathcal{D}_k(\underline{v}) = (v_{k+1}, \dots, v_K, \underbrace{0, \dots, 0}_{k \text{ times}})$$



Mathematical Analysis

General K

Arrival Transitions from State (i, j, \underline{v}) , $i \geq 0$, $j \leq (K - i)^+$

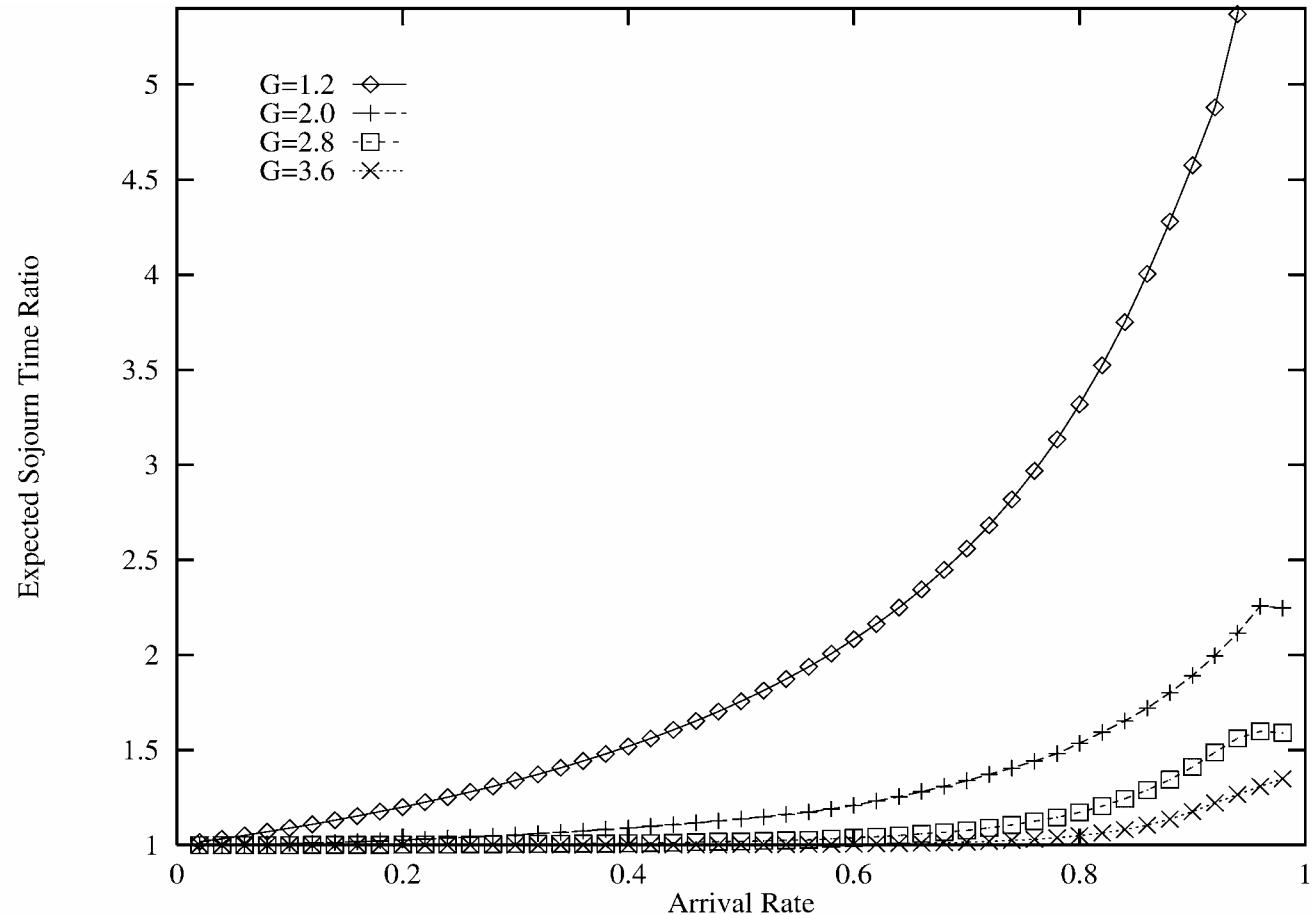
To State	Rate
$(i + 1, j - 1, \mathcal{A}_{i+1}(\underline{v}))$, $j > 0$	$j\theta$
$(i, j + 1, \underline{v})$, $i + j < T_s^\ell \leq K$	λ_s
$(i + 1, j, \underline{v})$, $i < K$, $i + j < K$	λ
$(i + 1, j, \underline{v})$, $K \leq i < T_s^u$	λ
$(i + 1, j, \underline{v})$, $i \geq T_s^u$	$\lambda(1 - p_s)$

$$\mathcal{A}_i(\underline{v}) = (v_1, v_2, \dots, v_{i-1}, 1, \underbrace{0, 0, \dots, 0}_{K-i \text{ times}}).$$

Numerical Results

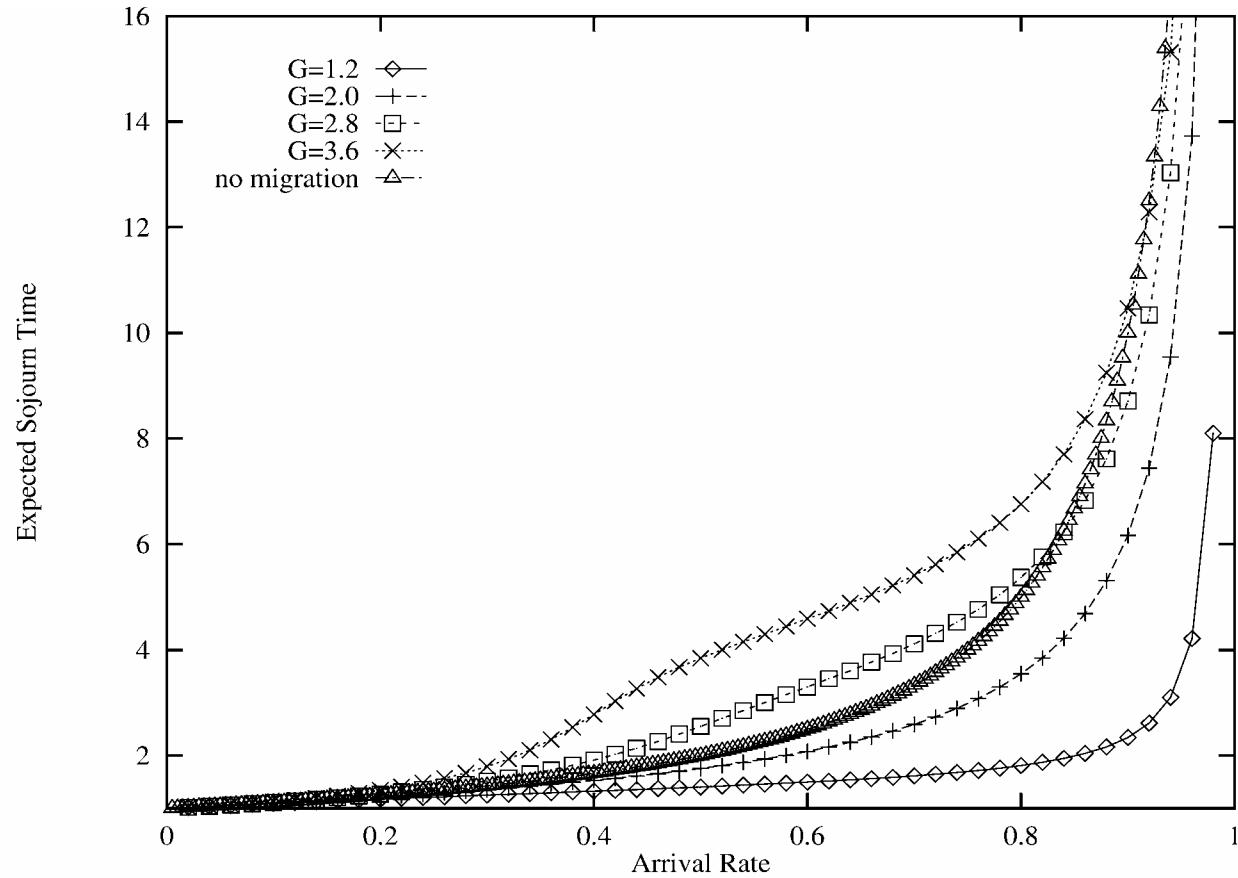
Optimal Threshold Values												
	$1/\gamma = 1.6$				$1/\gamma = 2.4$				$1/\gamma = 3.2$			
λ	\hat{T}_r^ℓ	\hat{T}_s^ℓ	\hat{T}_r^u	\hat{T}_s^u	\hat{T}_r^ℓ	\hat{T}_s^ℓ	\hat{T}_r^u	\hat{T}_s^u	\hat{T}_r^ℓ	\hat{T}_s^ℓ	\hat{T}_r^u	\hat{T}_s^u
0.04	1	1	1	1	0	1	-	2	0	1	-	3
0.08	1	1	1	1	1	1	2	2	1	1	3	3
0.12	1	1	1	1	1	1	2	2	1	1	4	4
0.16	1	1	1	1	1	1	2	2	1	1	4	4
0.20	1	1	1	1	1	1	3	3	1	1	4	4
0.24	1	1	1	1	1	1	3	3	1	1	5	5
0.28	1	1	1	1	1	1	3	3	1	1	5	5
0.32	1	1	1	1	1	1	3	3	1	1	5	5
0.36	1	1	1	1	1	1	3	3	1	1	5	5
0.40	1	1	1	1	1	1	3	3	1	1	6	6
0.44	1	1	1	1	1	1	3	3	1	1	6	6
0.48	1	1	1	1	1	1	4	4	1	1	6	6
0.52	1	1	1	1	1	1	4	4	1	1	7	7
0.56	1	1	1	1	1	1	4	4	1	1	7	7
0.60	1	1	1	1	1	1	4	4	1	1	8	8
0.64	1	1	1	1	1	1	4	4	1	1	8	8
0.68	1	1	2	2	1	1	4	4	1	1	8	8
0.72	1	1	2	2	1	1	5	5	1	1	9	9
0.76	1	1	2	2	1	1	5	5	1	1	9	9
0.80	1	1	2	2	1	1	5	5	1	1	10	10
0.84	1	1	3	3	1	1	6	6	1	1	10	10
0.88	1	1	3	3	1	1	7	7	1	1	12	12
0.92	1	1	4	4	1	1	9	9	1	1	12	12
0.96	1	1	12	12	1	1	12	12	1	1	12	12
0.98	1	1	12	12	1	1	12	12	1	1	12	12

Numerical Results



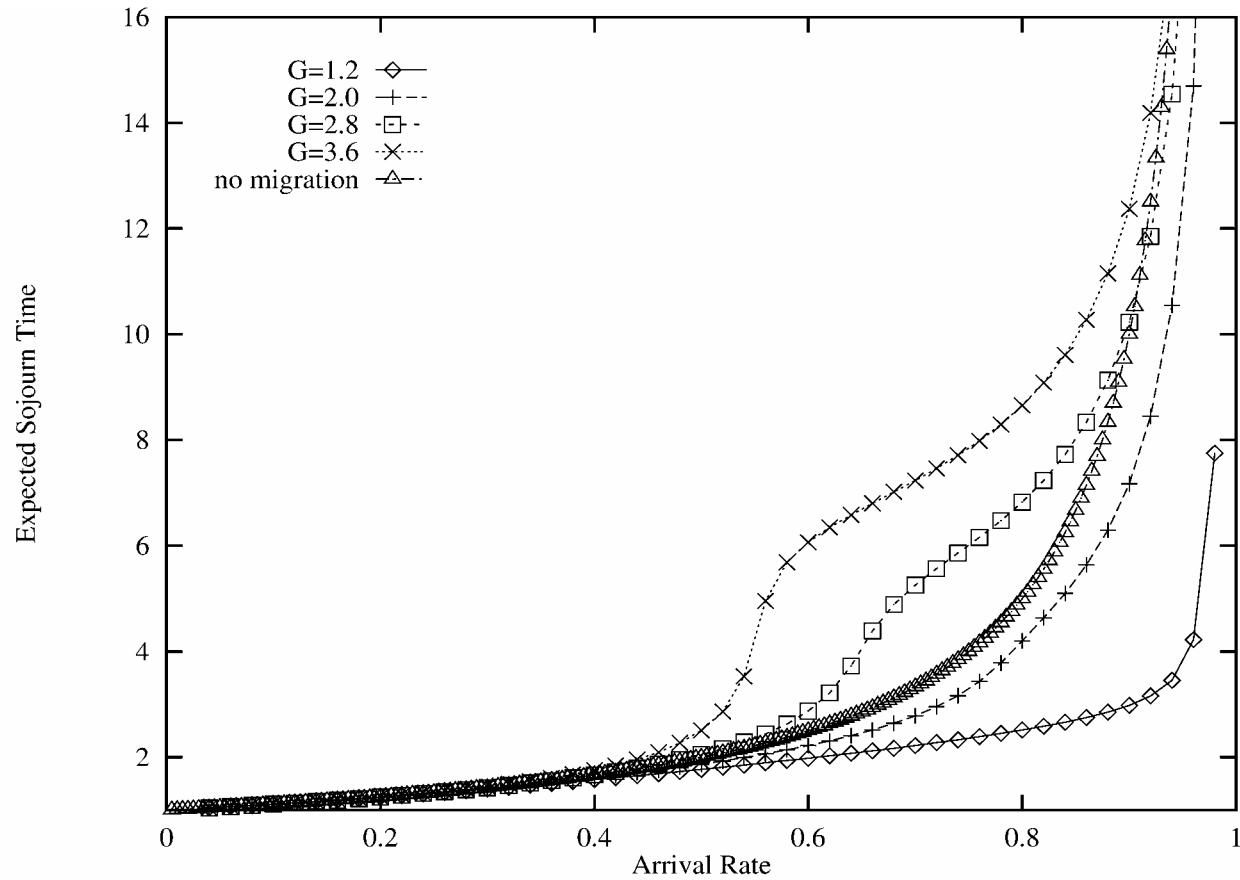
Relative Performance Benefits of the Migratory Scheduling Policy
with Optimal Thresholds over the No-Migration Policy

Numerical Results



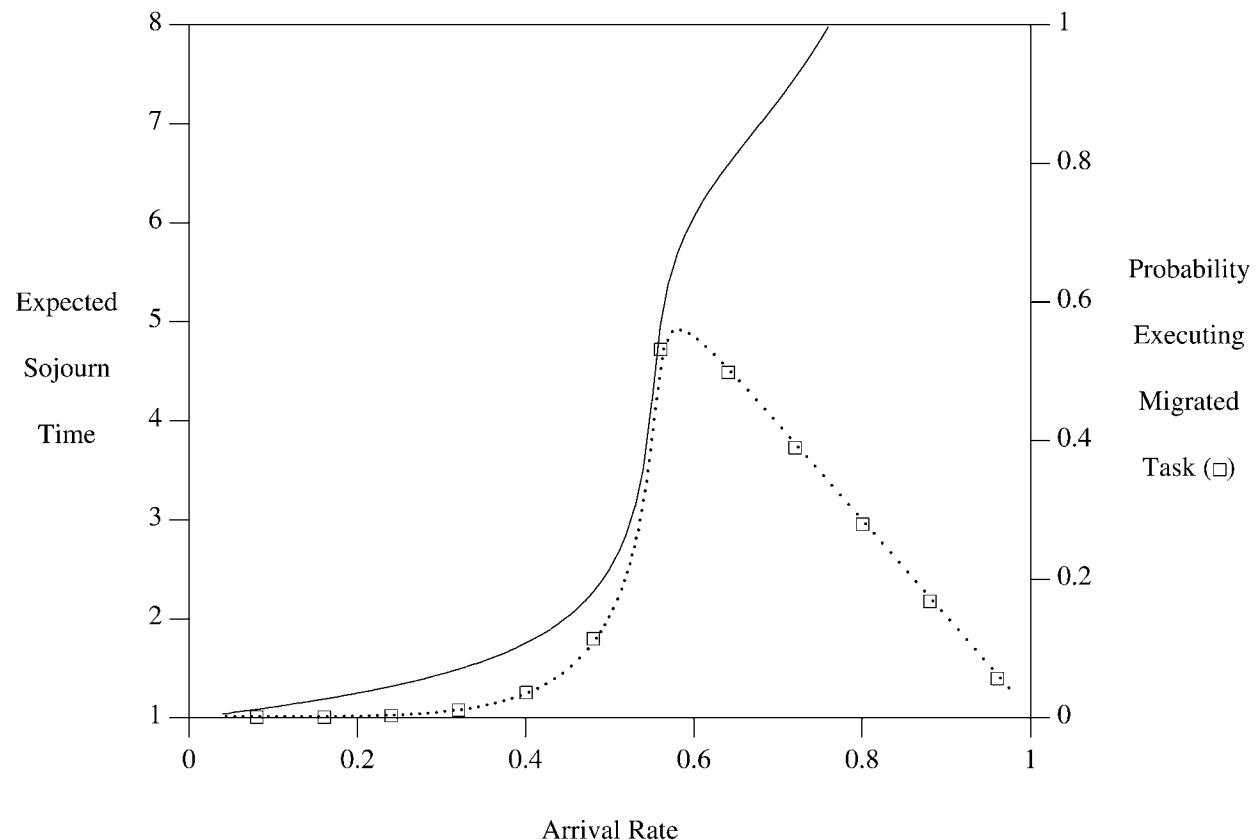
Expected Sojourn Times for the No-Migration Policy and the Migratory Scheduling Policy with Thresholds $\beta = (T_r^\ell, T_s^\ell, T_r^u, T_s^u) = (1, 1, 2, 2)$

Numerical Results



Expected Sojourn Times for the No-Migration Policy and the Migratory Scheduling Policy with Thresholds $\beta = (T_r^\ell, T_s^\ell, T_r^u, T_s^u) = (2, 2, 4, 4)$

Numerical Results



Expected Sojourn Time, and Probability of Executing a Migrated Task, for the Migratory Scheduling Policy with Thresholds $\beta = (T_r^\ell, T_s^\ell, T_r^u, T_s^u) = (2, 2, 4, 4)$



Stochastic Derivative-Free Optimization

- Internal Model

- External Model

- Trust Region



General Overview

- Optimal Scheduling Policy
 - Fluid control problem: $c\mu$ type scheduling policy
 - Brownian control problem: dynamic threshold-type scheduling policy
- Analysis of Dynamic Threshold Scheduling
 - Consider generalized threshold scheduling policy
 - Matrix-analytic analysis and fix-point solution, asymptotically exact
 - Numerical experiments
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- Stochastic Derivative-Free Optimization