

Online Optimization in practice

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PROFESSIONALS IN PLANNING -

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Problem Terminology



- q Online
 - § A problem whose data reveals itself step by step
 - S Not clear when (if ever) the input is complete
 - § Data may be only partially revealed
 - S Decision upon the course of action needs nevertheless to be taken... online!

q Dynamic

- § The system parameters change over time
- § An existing solution may become infeasible
- § Need to adjusted or completely change solutions over time

q Real-time

- S As soon as new data is known the solution must change
- S The speed of reaction may vary from immediate to quite soon

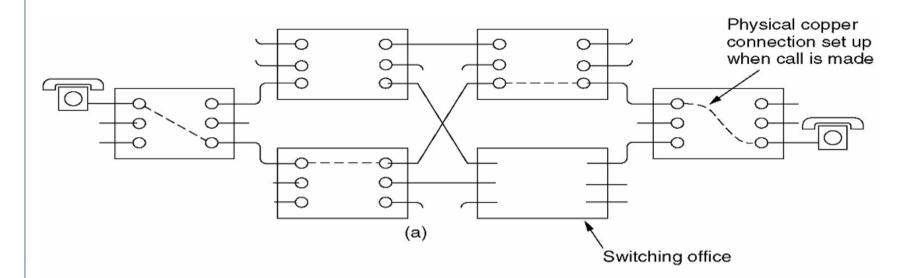
Problem categories



- $\ensuremath{\underline{\mathrm{q}}}$ Continuous optimization
 - $\mathbb{S} ABS$
 - S Computer assisted avionics
 - S Space craft atmosphere re-entry
- $\ensuremath{\underline{\mathrm{q}}}$ Combinatorial optimization
 - S Circuit switching
 - S Packet switching
 - S Pickup and delivery with rolling planning horizon
 - § Dial a Ride

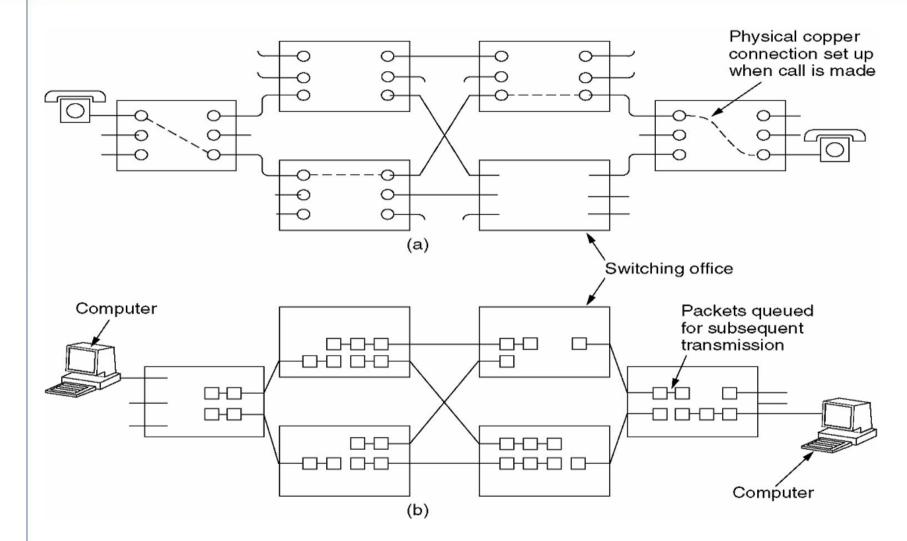




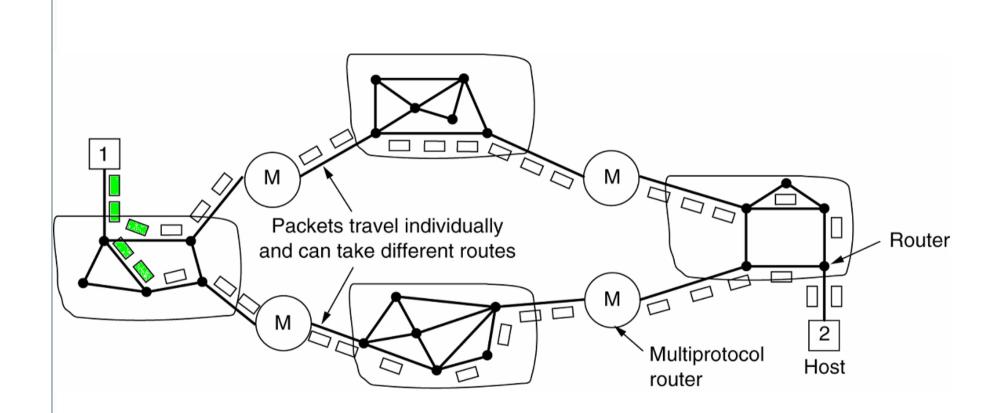




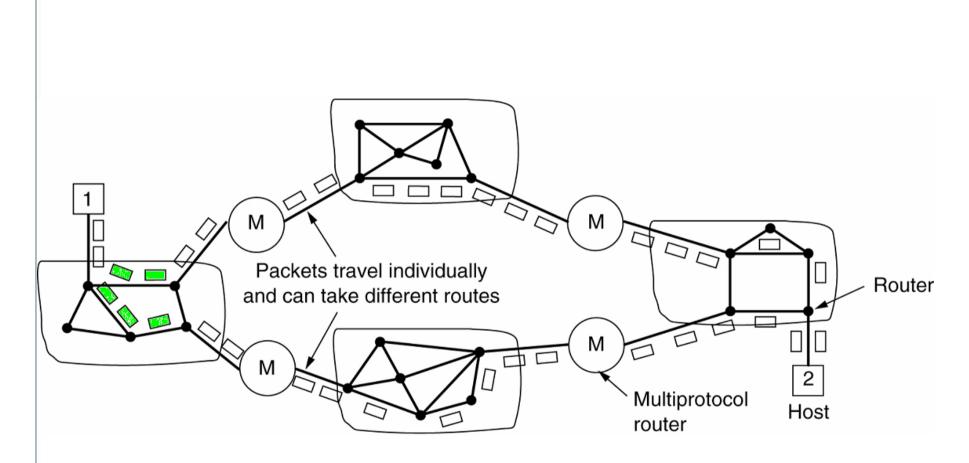




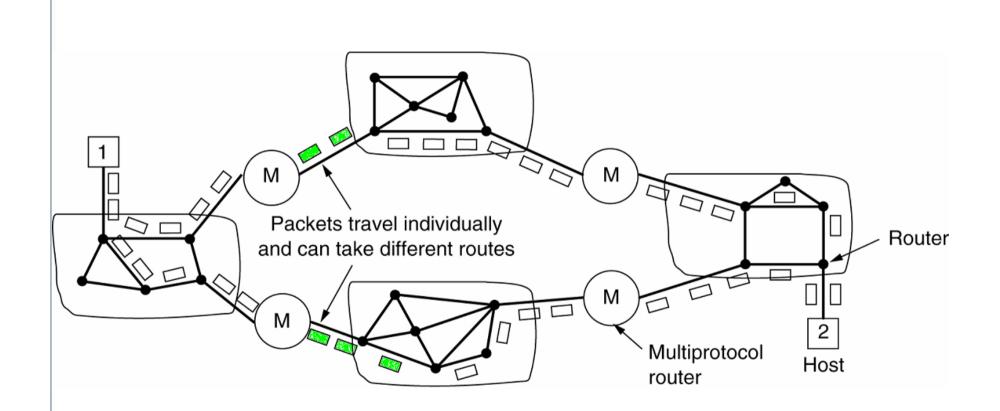




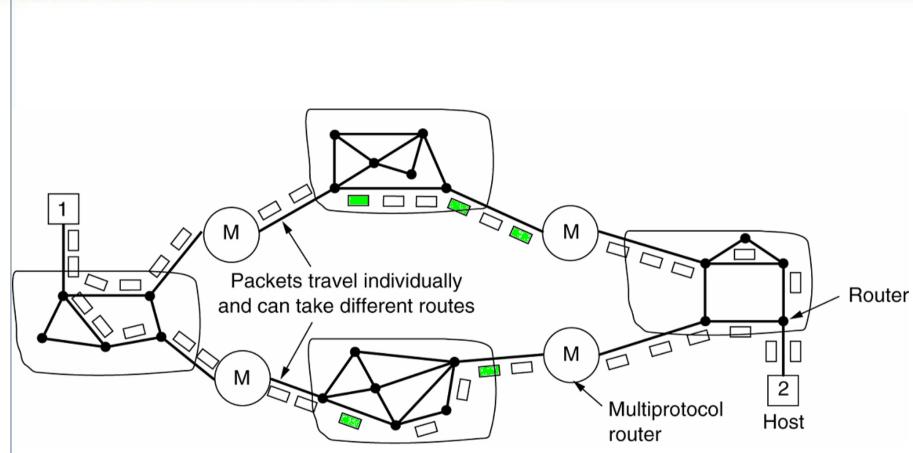




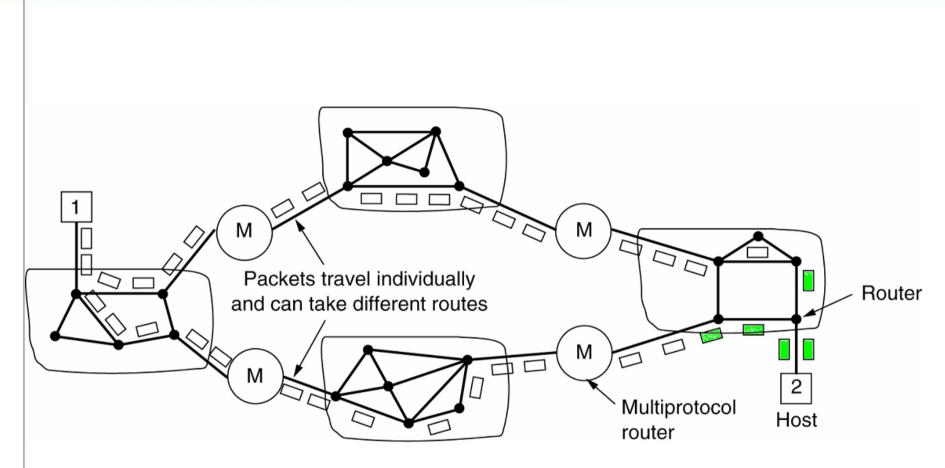






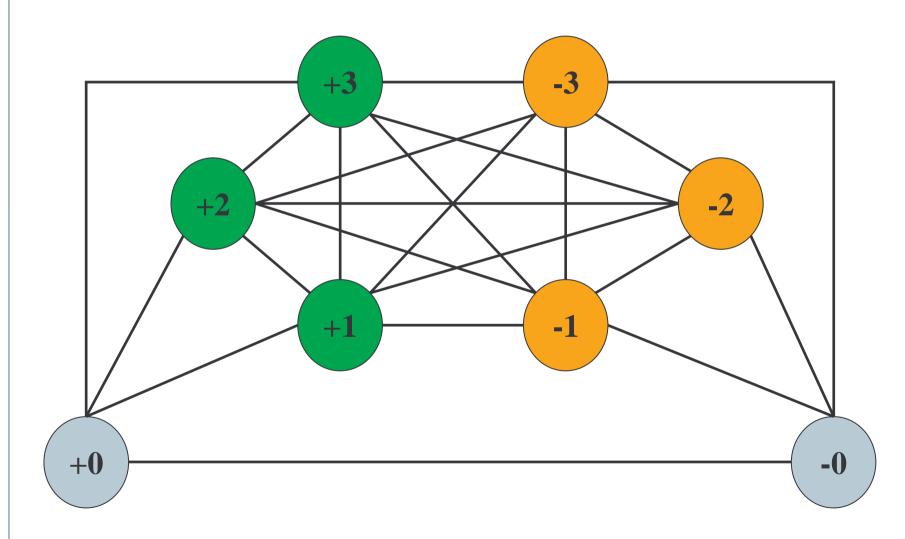






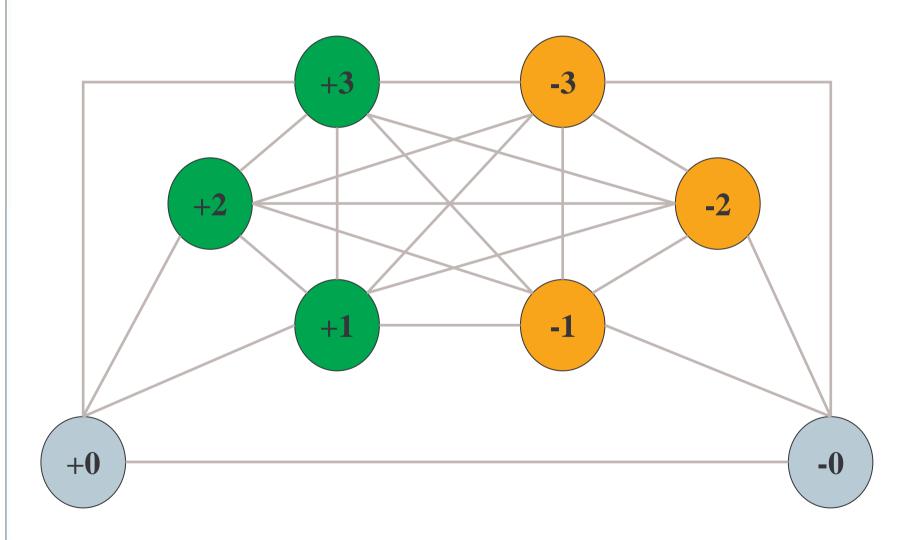


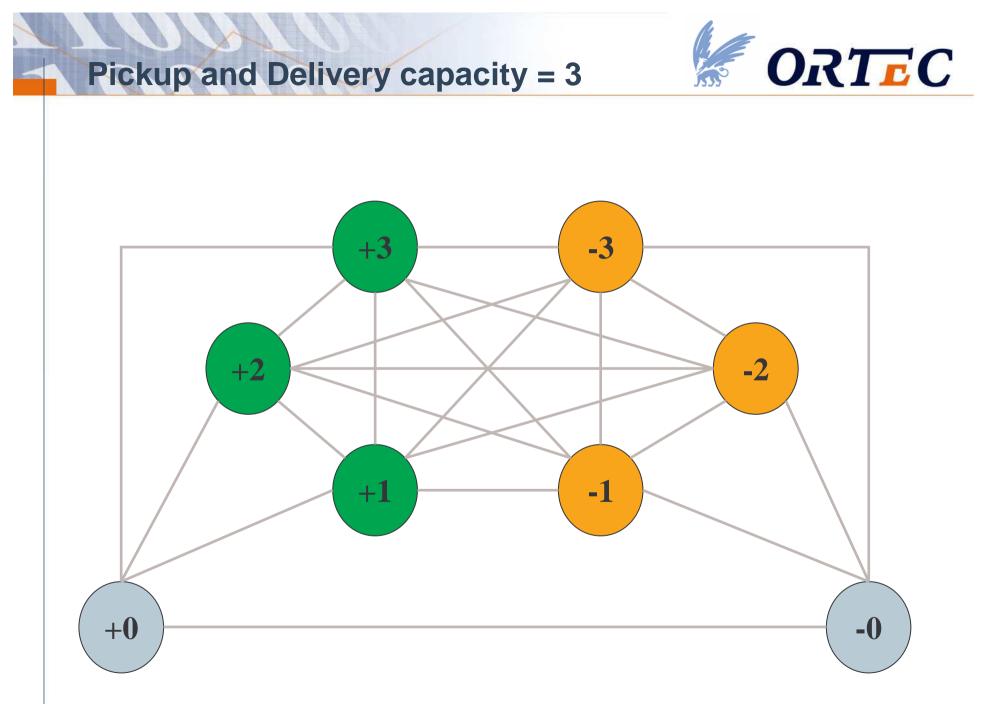


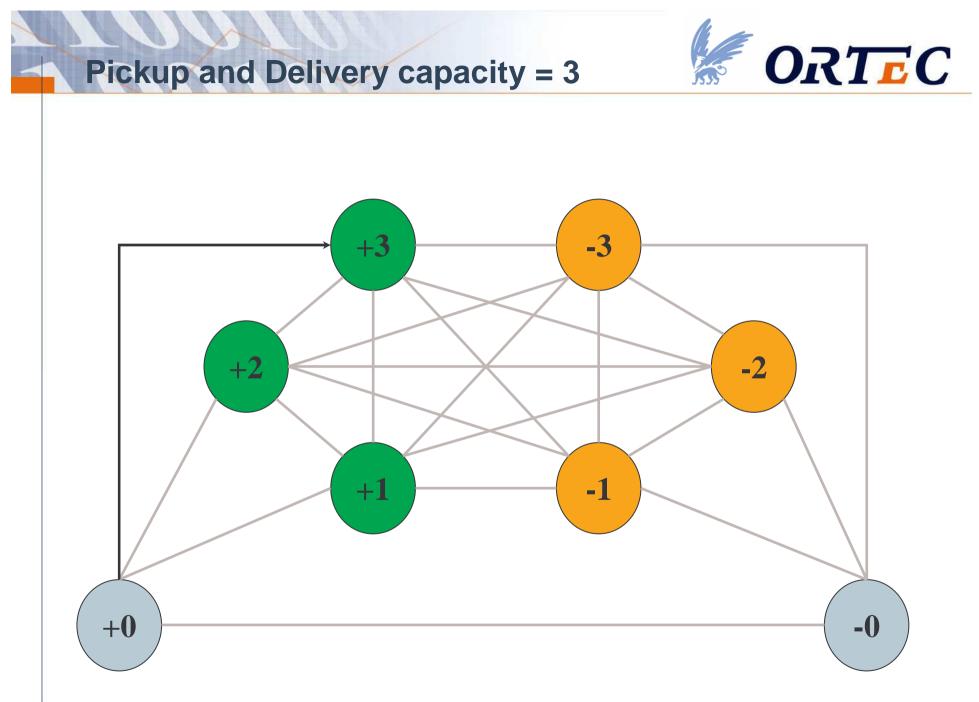


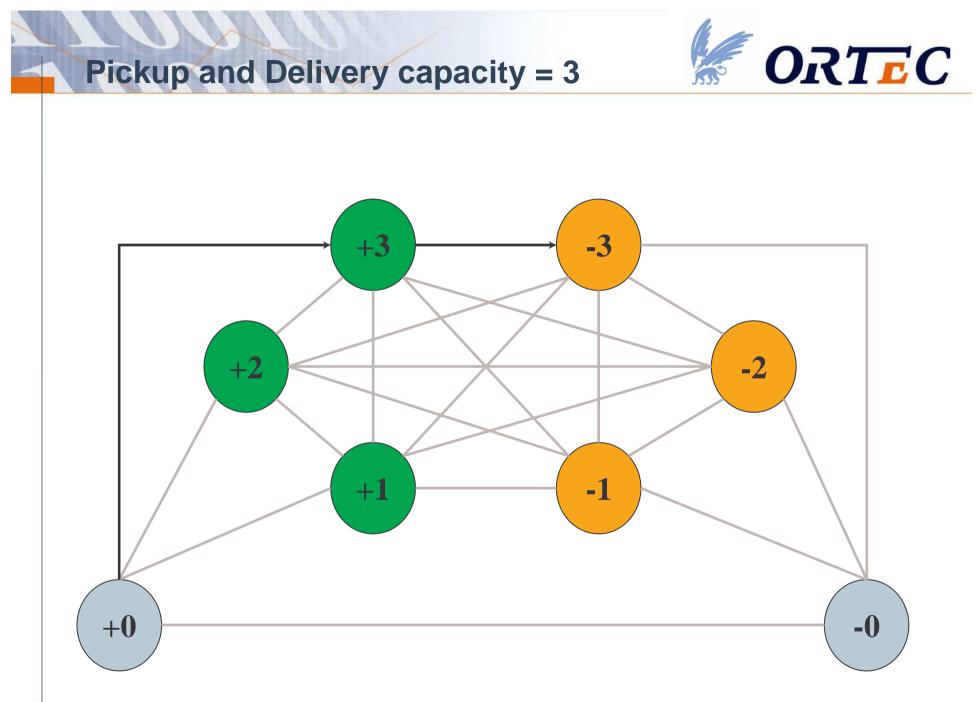


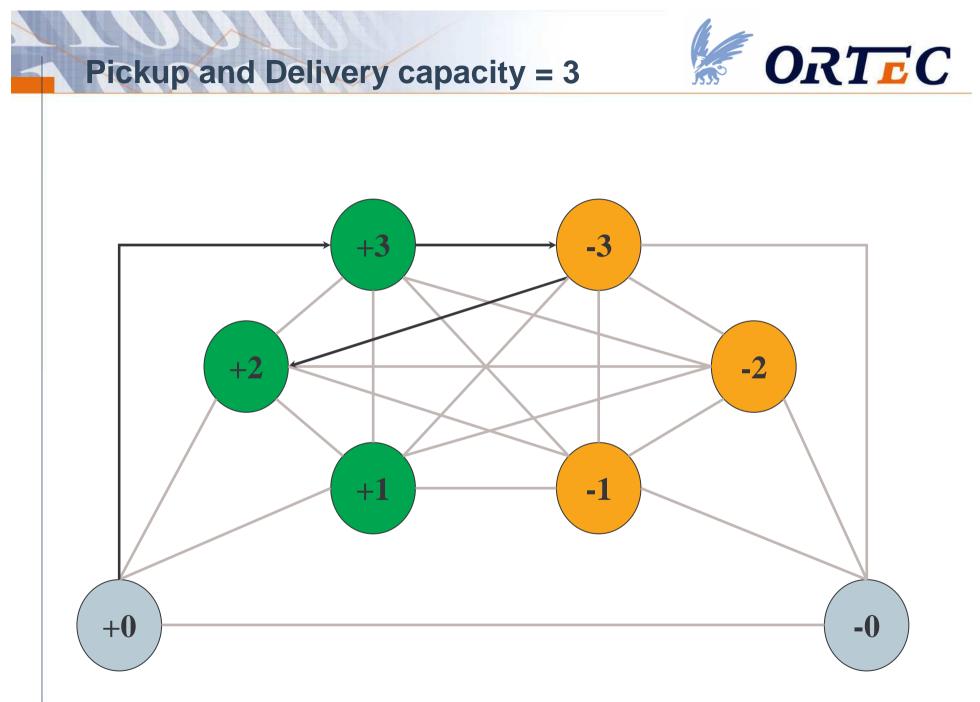


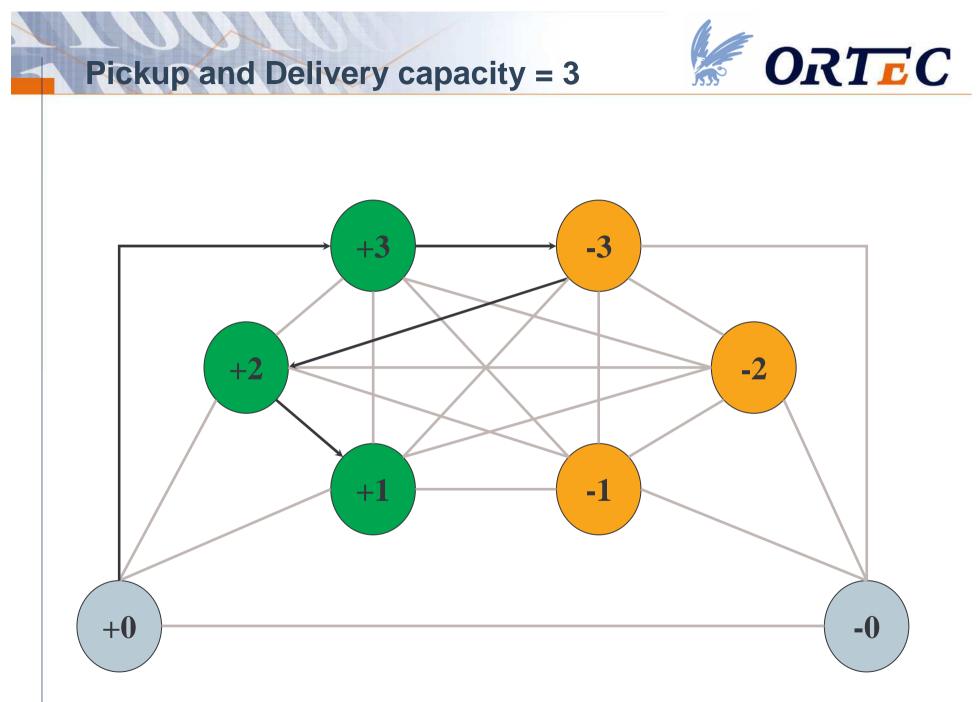


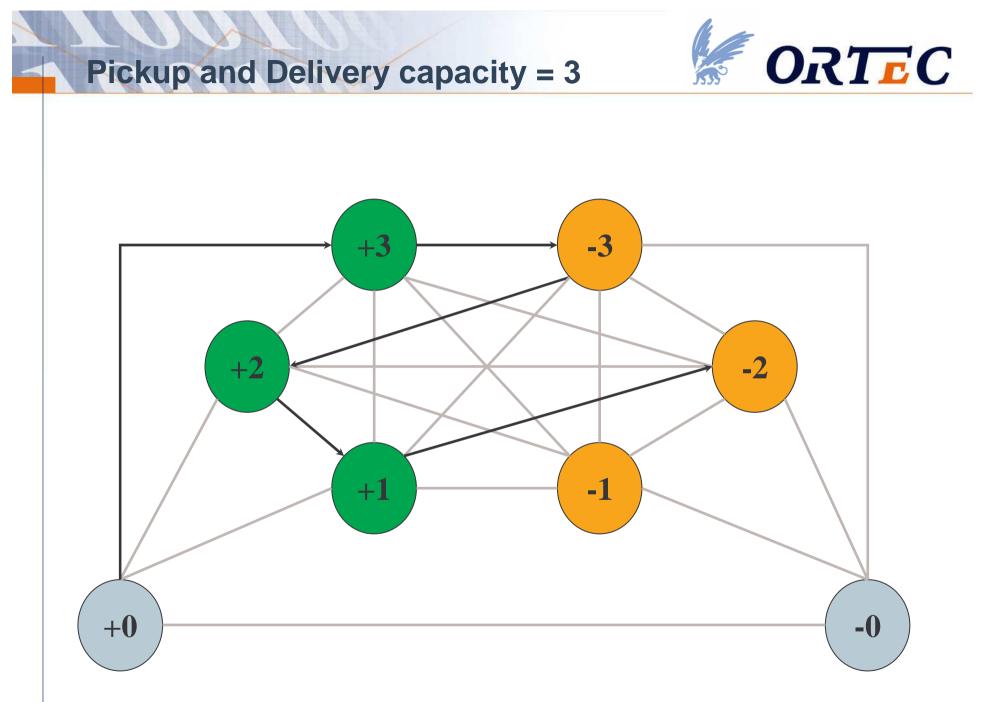


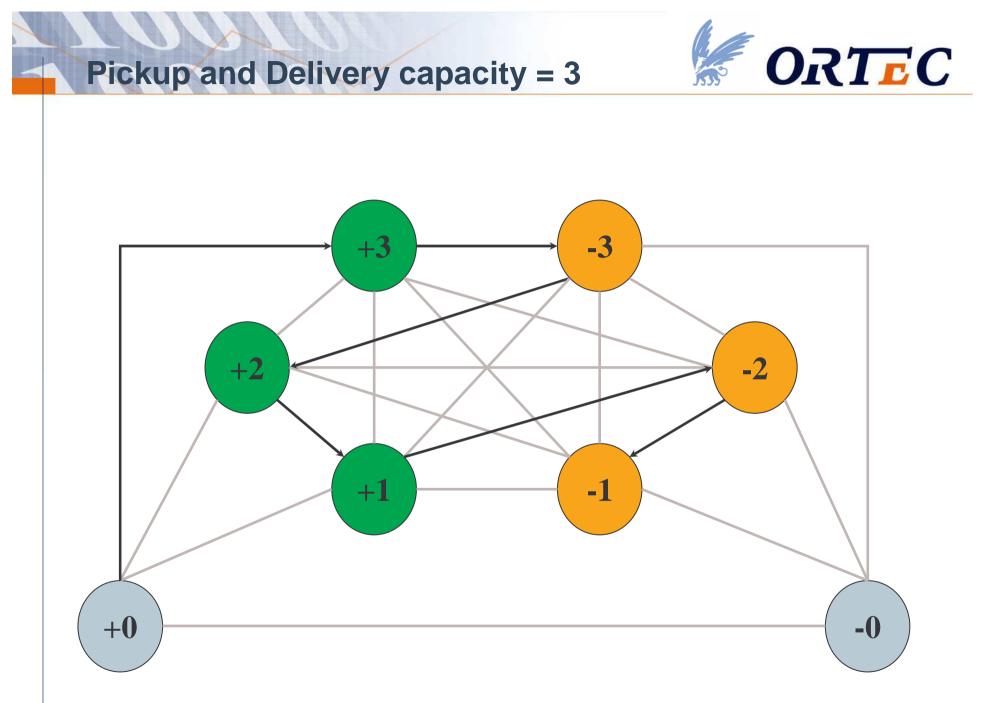


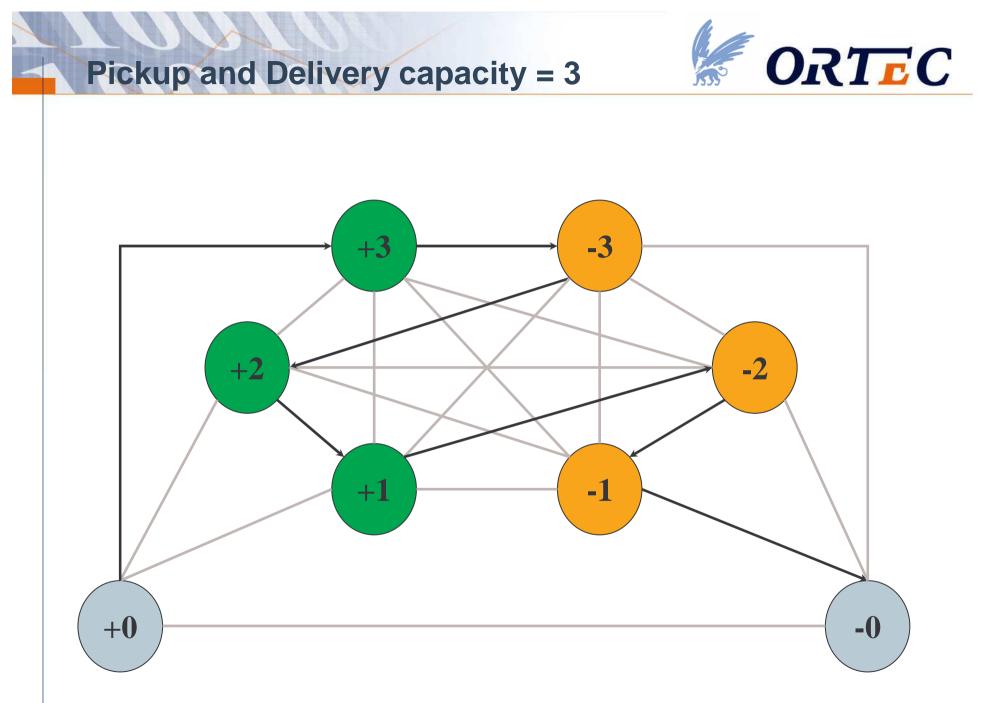


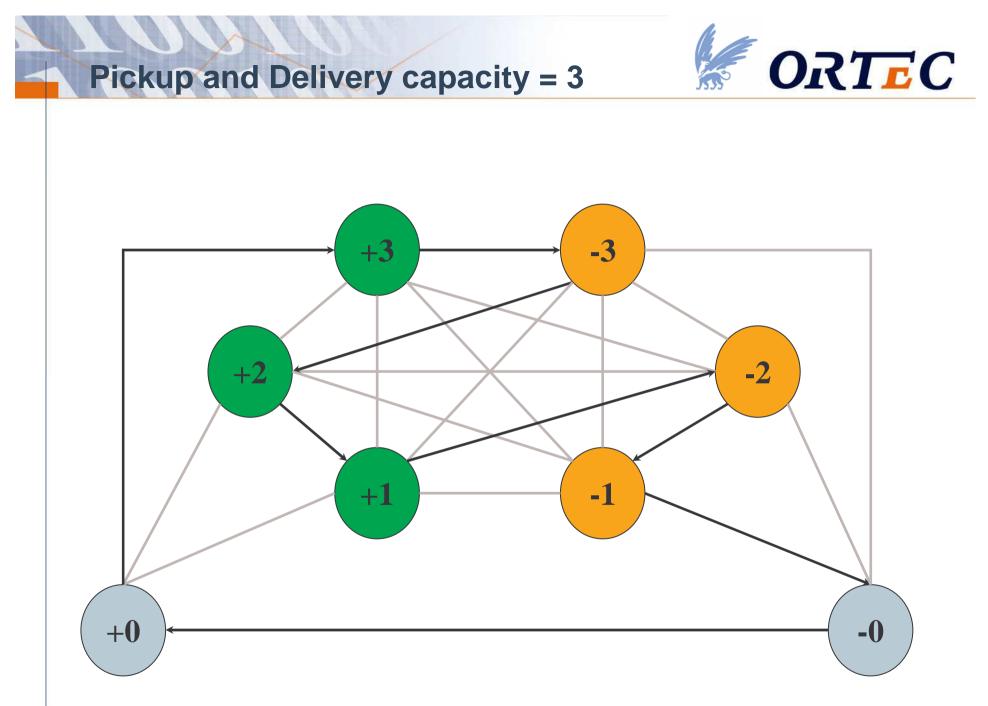


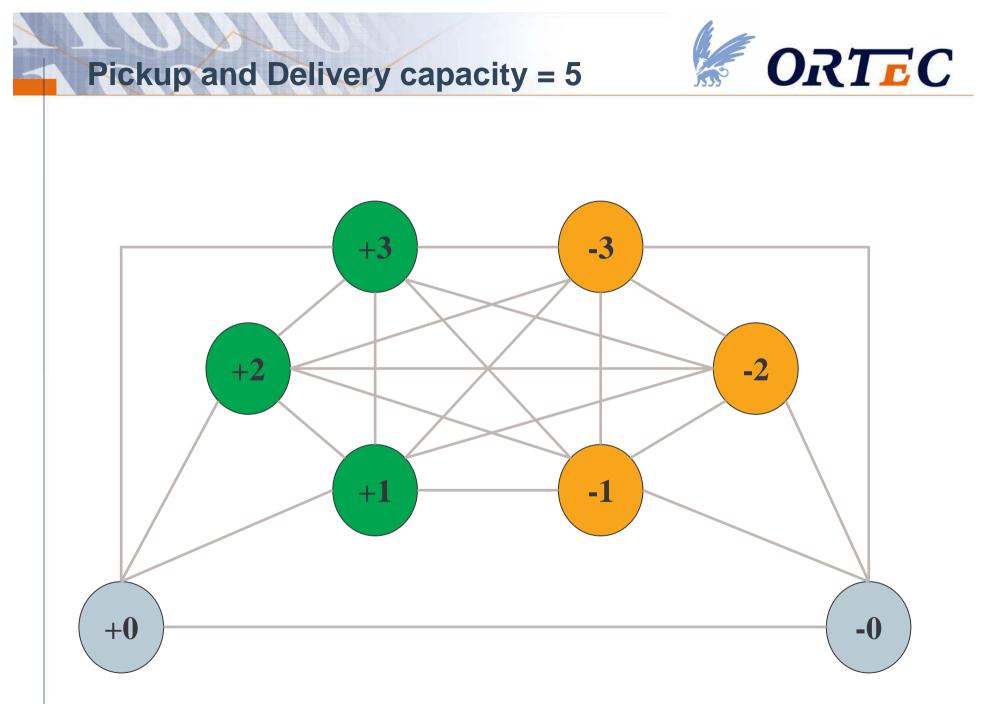


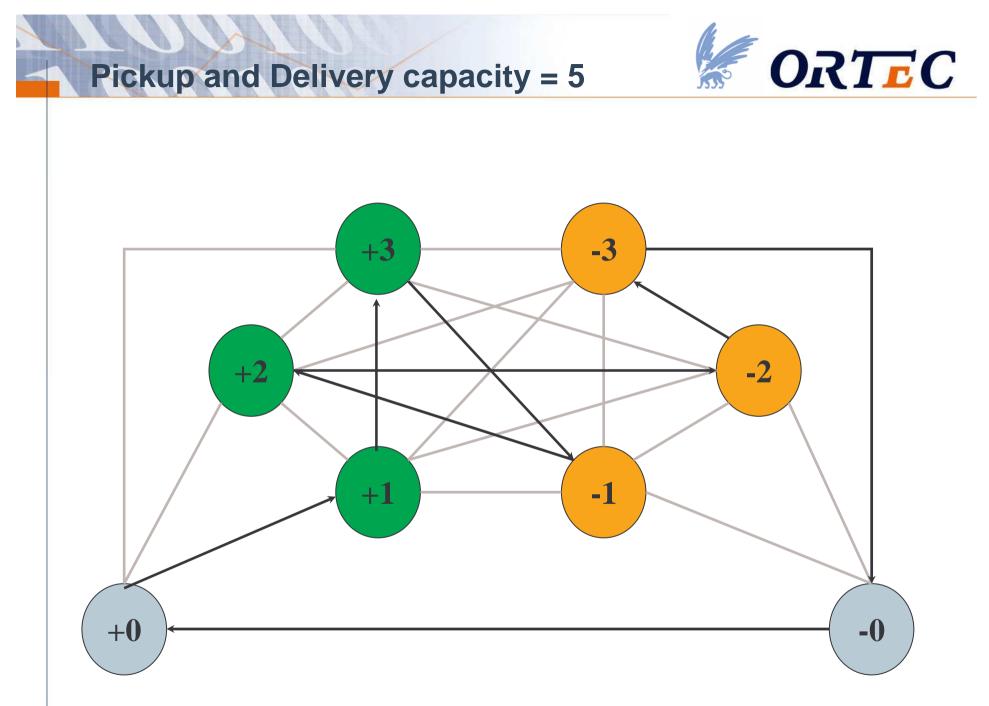




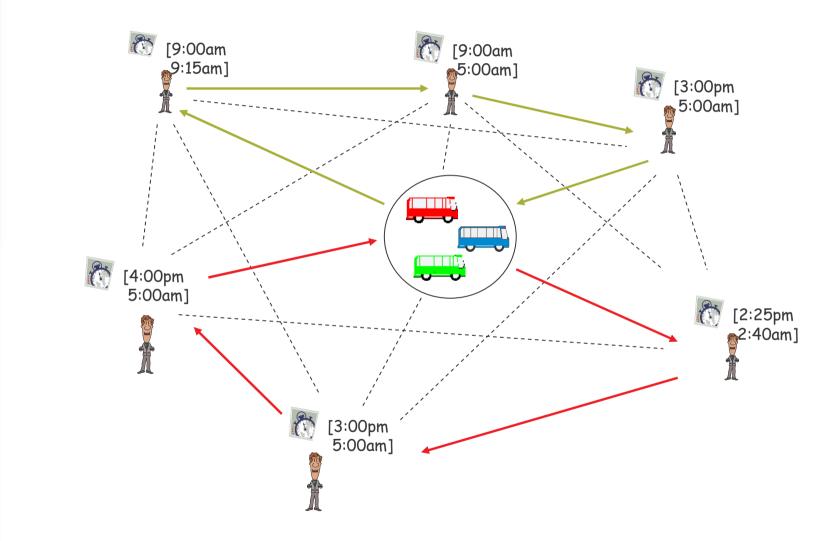








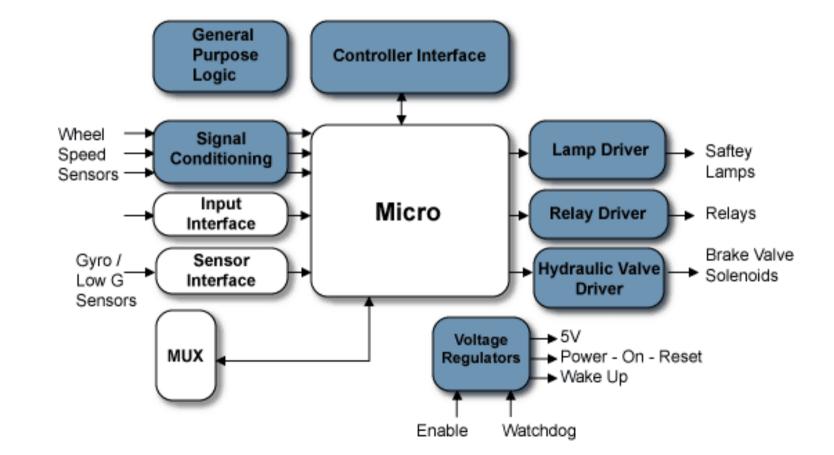




Dial a ride

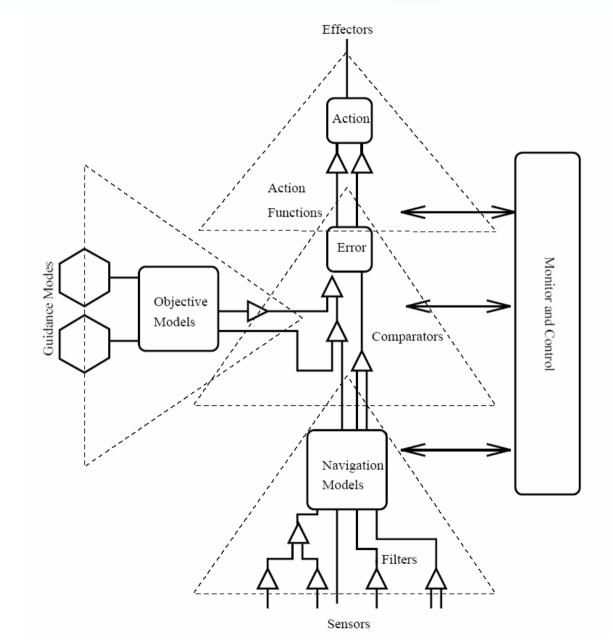






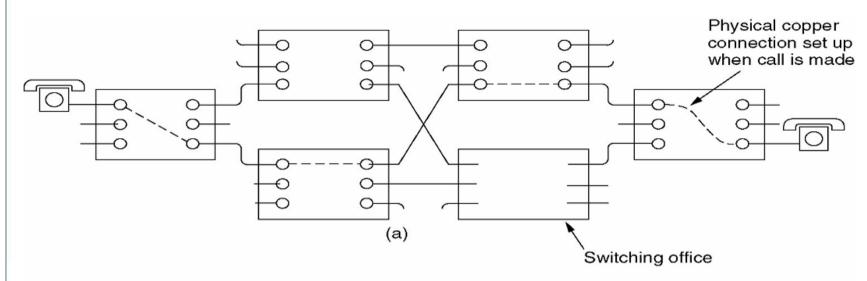






Circuit switching

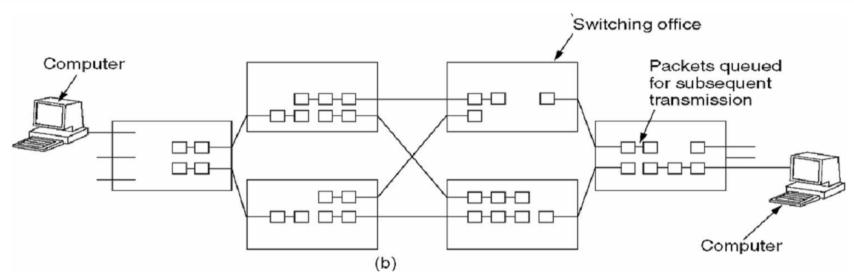




- Physical infrastructure does not change very often:not very dynamic
- ণু Connection set up almost immediately: *real-time*
- ণ The call schedule is unknown and the horizon is open: online
- Provide<t
- g The system works automatically and without human intervention: unattended control



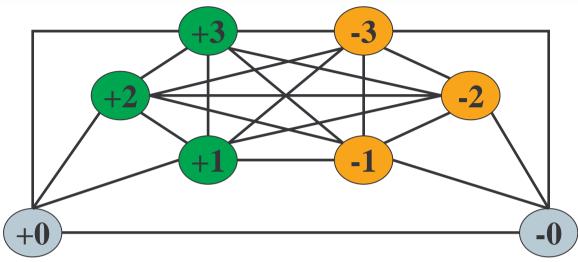




- qThe Internet changes dramatically and constantly:very dynamic
- ণু Connection set up almost immediately: *real-time*
- Provide the communication demands are unknown and the horizon is open:Openation on the interval of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon is open.Openation of the communication demands are unknown and the horizon demands are unknown and the horizon demands are unknown and the horizon demands are unknown are
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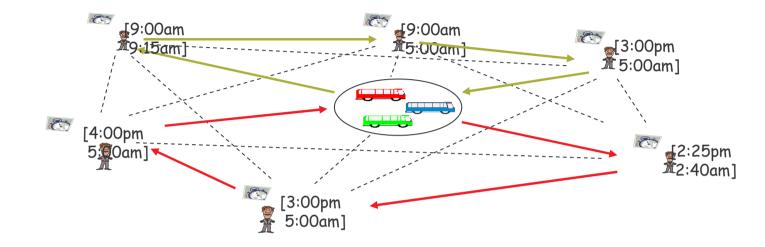


- Provide the second se
- ু Take a courier: new orders need to be dispatched quickly: *real-time*
- Provide and the planning horizon is open:Provide and the planning horizon is open:Openation on line
- q A solution involves many choices:combinatorial

q A typical setting involves one or more human planners:decision support

Dial a Ride revisited



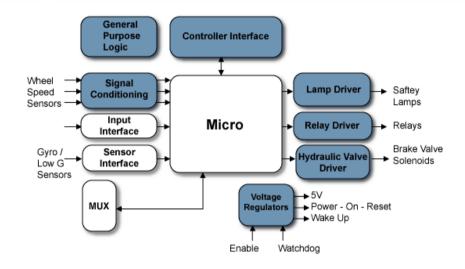


- qTravel speeds may depend on traffic congestion:dynamic
- ু New orders need to be dispatched quickly: *real-time*
- Provide and the planning horizon is open:Provide and the planning horizon is open:Openant Contine
- ମ୍ବ A solution involves many choices: combinatorial

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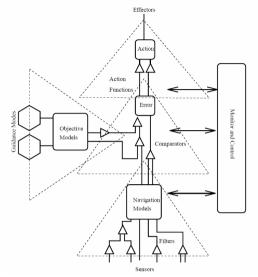
ABS and Traction control revisited



- qSystem components are stable and fixed:not very dynamic
- ণ্ৰ Immediate response needed: *real-time*
- Provide<t
- qThe optimal course of action is a control of continuous variables:continuous
- g The system works automatically and without human intervention: unattended control



ABS and Traction control revisited



- qSystem components are stable and fixed:not very dynamic
- ণ্ৰ Immediate response needed: *real-time*
- ণ Value of the different parameters changes continuously: online
- qThe optimal course of action is a control of continuous variables:continuous
- Provide<t

Facts and chalenges



- q A good approach to a new situation involves:
 - 1. Problem analysis
 - 2. Model identification
 - 3. Algorithm development
 - 4. Implementation
- qOften the same person(s) are involved through the full
approach
- qThe needed skills are hard to master and oftenimpossible to combine
- qEspecially in software development the first steps tendto be neglected.
- q Especially step 2 is often ignored
- q Most real life decision problems are online by nature
- q Often they are approached offline
- q An offline deliberately ignores future developments





- Image: Provide the second structureImage: Provide the second structure<
- $\ensuremath{\underline{\mathrm{q}}}$ This is usually used as an advantage
- qThe system computes a few alternatives and lets the
planner choose

From the planner's prespective...



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