

Beating the curse of dimensionality in options pricing and optimal stopping

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LNMB

Outline

- 1 **Punchline**
- 2 **Model + Problem**
- 3 **Intuition + Main results**
- 4 **Future Research**

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- Opt. pricing and opt. stopping central to Fin. Math, OR, AP
- Rich history in NL → Amsterdam Bourse in 1600's
- Many real-world comp. problems have ...

- Leads to Curse of dimensionality

- Opt. dual martingales hard to understand explicitly
- Many approaches need fully nested cond. exp.

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- We prove ...
 - \exists “simple and elegant formula” for opt. stop. as ∞ sum
 - Even better, if you truncate the sum after k terms ...
 - Easy to understand
 - Easy to implement
 - Yields efficient rand. ϵ -optimal algorithms
 - Running time $\tilde{O}(n^2/\epsilon)$
 - Data-oblivious $\tilde{O}(n^2/\epsilon)$ samples
 - Even with $\log(n)/\epsilon$ and $\log(1/\epsilon)$ dependencies
 - Better than state-of-the-art deterministic algorithms
 - ϵ -optimal for general FTF target and ϵ sample
 - New connection to net. flows
 - ϵ -optimal via simple greedy dual ascent and
 - Potential new hammer

Punchline

- We prove ...
 - \exists “simple and elegant formula” for opt. stop. as ∞ sum
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 - ✦ Easy to implement
 - Yields efficient rand. ϵ -optimal algorithms
 - ▶ ϵ -optimal in $\frac{1}{\epsilon}$ steps
 - ▶ ϵ -optimal in $\frac{1}{\epsilon}$ samples
 - ▶ ϵ -optimal in $\frac{1}{\epsilon}$ oracle calls
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 - Runtime $T^{rand}(\epsilon)$
 - Approximation error ϵ
 - Problem size n
 - Problem complexity κ
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 - Runtime $\mathcal{T}^{\text{poly}}(\frac{1}{\epsilon})$
 - Data-driven : $\mathcal{T}^{\text{poly}}(\frac{1}{\epsilon})$ samples
 - Even with high-dim and path-dependence
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 - (sample-based) PTAS for gen. opt. stop
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Model

- Discrete time : T periods
- $\mathcal{F} = \{\mathcal{F}_t, t \in [1, T]\}$ gen. by D -dim process $\mathbf{Y} = Y_1, \dots, Y_T$
- Cost functions $\{g_t, t \in [1, T]\}$

● Z_t : set of \mathcal{F}_t -measurable random variables

● \mathcal{T} : set of \mathcal{F} -adapted stop.times in $[1, T]$

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- Note: Sometimes assume $Z_t \in [0, 1]$ or $[0, U]$

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 - $Z_t \stackrel{\Delta}{=} g_t(Y_{[t]}) = \text{cost of stop. at } t$
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- $\inf_{\tau \in \mathcal{T}} E[Z_\tau]$
 - Full path-dependence
 - High dimensionality
 - Massive state space
 - Gen. disc-time optimal stopping
 - Pricing Bermudan Options
 - Fundamental problem in control theory
 - WLOG generally discuss the min. problem
 - Can transform max to min
 - Ideas are clearer for min
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Outline

- 1 Punchline
- 2 Model + Problem
- 3 Intuition + Main results**
- 4 Future Research

Main intuition

- $\text{OPT} \triangleq \inf_{\tau \in \mathcal{T}} E[Z_\tau]$
- $\text{OPT} = \inf_{\tau \in \mathcal{T}} E[Z_\tau] \geq E[\min_{t \in [1, T]} Z_t]$
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Fast convergence

- THEOREM : $|\text{OPT} - \sum_{i=1}^k E[\min_{t \in [1, T]} Z_t^i]| \leq \frac{U}{k+1}$
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- $E[\min_{t \in [1, T]} Z_t^k]$ can be computed by sim!
- No curse of dimensionality!
- Completely data-driven
- Recursive, complexity \uparrow in k
- But only need a few terms!
- Explicit runtime depends on assumptions + type of approx.
- In general ϵ -approx for OPT in $T^{\text{poly}(\frac{1}{\epsilon})}$ time! (w.h.p.)
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 - \approx Stop when $Z^{\text{poly}(\frac{1}{\epsilon})}$ goes below ϵ

Algorithmic implications

- $E[\min_{t \in [1, T]} Z_t^k]$ can be computed by sim!
- No curse of dimensionality!
- Completely data-driven
- Recursive, complexity \uparrow in k
- But only need a few terms!
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Algorithmic implications (cont.)

“Canonical” Theorem

- Suppose $P(Z_t \in [0, 1]) = 1$ for all t .
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- Returns r.v. X s.t.

$$P(|X - \text{OPT}| \leq \epsilon) \geq 1 - \delta.$$

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- A correspondence between opt. stop and min-cut
- Illustrate in trivial 3-stage problem
 - Driving process Y is 1-d, supp. $\{1, 2\}$
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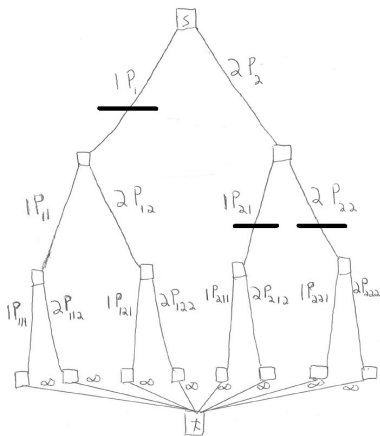
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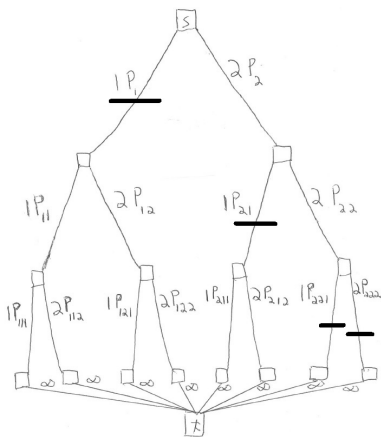


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- OBS : Simple proofs and intuition about many past results
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Outline

- 1 Punchline
- 2 Model + Problem
- 3 Intuition + Main results
- 4 Future Research**

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- Fast implementation and comparison to past approaches
- Glasserman, Longstaff-Schwartz, Andersen and Broadie, Belomestny, Schoenmakers, Bender, Christensen, Ibanez, Jamshidian, Farias, Kohler, Lelong, . . .
- Especially on real financial data and problems
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- Better understanding of conv.
 - Smarter algs. with better sim. techniques
 - Gen. to mult. stop. , stoch. con., cont. time, ∞ horizon, ...
 - Lower bounds, comp. complexity, randomization
 - Modified / different such expansions
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 - Application to other stopping problems
 - From queueing (see also Ghitany)
 - From Call center man, choice mod., etc.
 - From control, robotics, etc.
 - From sports and games
 - New applications
- New potential hammer - interesting nails?
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 - Note: our approach a kind of proph. ineq.
- New potential hammer - interesting nails?
- Thanks!

Future research cont.

- Better understanding of conv.
- Smarter algs. with better sim. techniques
- Gen. to mult. stop. , stoch. con., cont. time, ∞ horizon, ...
- Lower bounds, comp. complexity, randomization
- Modified / different such expansions
- Other tools from network flows
- Application to other stopping problems
 - Probs. from seq. stat. (esp. Gittins!)
 - Probs. from OM, rev. man, choice mod., etc.
 - Probs. from control, robotics, etc.
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Extra credit : fast convergence proof

- Recall : $Z_t^k = Z_t^{k-1} - E[\min_{i \in [1, T]} Z_i^{k-1} | \mathcal{F}_t]$
- Claim : $Z_t^k \geq 0$ for all t, k
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- THEOREM : $|\text{OPT} - \sum_{i=1}^k E[\min_{t \in [1, T]} Z_t^i]| \leq \frac{U}{k+1}$
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