Networks — an OR perspective

Michel Mandjes^{1,2,3}

¹Korteweg-de Vries Institute for Mathematics, University of Amsterdam ²CWI, Amsterdam ³Eurandom, Eindhoven

> Back-to-School day January 14th 2016

Lunteren, the Netherlands

This Back-to-School day is on networks.

This Back-to-School day is on networks.

 Networks arguably form the main concept in operations research,

This Back-to-School day is on networks.

- Networks arguably form the main concept in operations research,
- with the ultimate goal to devise procedures for optimal design (long time scale) and operations (short time scale).

Virtually any networks-related problem has *combinatorial/deterministic* and *stochastic* elements.

Virtually any networks-related problem has *combinatorial/deterministic* and *stochastic* elements.

Often:

Virtually any networks-related problem has *combinatorial/deterministic* and *stochastic* elements.

Often:

- Combinatorial/deterministic techniques needed to design network such that demand is met on the longer term;
- Stochastic techniques needed to assess whether random (short term) fluctuations are adequately dealt with.

... but in reality things are more subtle:

... but in reality things are more subtle:

 setting up algorithms to deal with short-term fluctuations often requires combinatorial techniques (think of scheduling),

... but in reality things are more subtle:

- setting up algorithms to deal with short-term fluctuations often requires combinatorial techniques (think of scheduling),
- and also in the design phase uncertainty is typically already included.

At a 'stylized' level, OR has developed a set of generic models and concepts that fit in many situations — think of

At a 'stylized' level, OR has developed a set of generic models and concepts that fit in many situations — think of

 various sorts of standard queueing models (e.g., GI/G/c, fluid queues),

At a 'stylized' level, OR has developed a set of generic models and concepts that fit in many situations — think of

- various sorts of standard queueing models (e.g., GI/G/c, fluid queues),
- various sorts of standard combinatorial structures (graphs, matchings, travelling salesman),

At a 'stylized' level, OR has developed a set of generic models and concepts that fit in many situations — think of

- various sorts of standard queueing models (e.g., GI/G/c, fluid queues),
- various sorts of standard combinatorial structures (graphs, matchings, travelling salesman),
- various sorts of scheduling models,

etc.

but . . .

but . . .

stylized models are limited: new (variants of existing) models keep on being studied, called for by new developments in the application domains.

but . . .

- stylized models are limited: new (variants of existing) models keep on being studied, called for by new developments in the application domains.
- size: networks become larger (increasingly connected world, with more data available). Requires structural understanding of such large networks, and powerful computational techniques.

but . . .

- stylized models are limited: new (variants of existing) models keep on being studied, called for by new developments in the application domains.
- size: networks become larger (increasingly connected world, with more data available). Requires structural understanding of such large networks, and powerful computational techniques.
- not stand-alone: increasing awareness that stochastic and deterministic issues should not be dealt with separately. Along the same lines: link with theoretical computer science, data science, statistics (think of simultaneous estimation and optimization), etc.



December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks.



December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks. Runs from 2014 till 2024.



December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks. Runs from 2014 till 2024.

Focuses on understanding and optimizing large complex networks.



December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks. Runs from 2014 till 2024.

Focuses on understanding and optimizing large complex networks. Math/cs teams Univ. of Amsterdam, CWI, Eindhoven, Leiden.

NET WORKS

December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks. Runs from 2014 till 2024.

Focuses on understanding and optimizing large complex networks. Math/cs teams Univ. of Amsterdam, CWI, Eindhoven, Leiden. Big volume (7 TTers, \pm 50 PhD students, \pm 20 postdocs, \pm 20 local staff involved).

NET WORKS

December 2013: large grant for fundamental research was awarded for research on (stochastic and combinatorial) analysis of networks. Runs from 2014 till 2024.

Focuses on understanding and optimizing large complex networks. Math/cs teams Univ. of Amsterdam, CWI, Eindhoven, Leiden. Big volume (7 TTers, \pm 50 PhD students, \pm 20 postdocs, \pm 20 local staff involved).

Surrounded by practical domain-specific projects.

Have a look at http://www.thenetworkcenter.nl

Content of today very much in line with mentioned trends. Six talks with new developments, seen from theoretical as well as practical angle.

- 10.40 11.20 The power of social network analysis Ana Barros (TNO).
- 11.35 12.15 The hub-network of KLM: importance and successfactors *Pieter Cornelisse* (KLM).
- 13.30 14.10 Design and operational challenges of communication networks - *Richa Malhotra* (SURFnet).
- 14.10 14.50 Supply Network Analytics Operations Research in the Supply Chain Jan van Doremalen (CQM).
- 15.05 15.45 Design and analysis of container liner shipping networks *Rommert Dekker* (Erasmus University Rotterdam).
- 15.45 16.25 Towards data-driven models for the mobility system *Maaike Snelders* (TNO and TU Delft).

A STOCHASTIC NETWORK...

At an abstract level a stochastic network can be seen as

A STOCHASTIC NETWORK...

At an abstract level a stochastic network can be seen as

a set of connected resources,

A STOCHASTIC NETWORK...

At an abstract level a stochastic network can be seen as

- a set of connected resources,
- used by customers, imposing a randomly fluctuating demand.





Class 0 uses node A and B,



Class 0 uses node A and B, class 1 node A,



Class 0 uses node A and B, class 1 node A, and class 2 node B.

This model is still rather imprecise:

This model is still rather imprecise:

How do customers arrive (Poisson process?), and what is the distribution about the amount of work they bring along?

This model is still rather imprecise:

- How do customers arrive (Poisson process?), and what is the distribution about the amount of work they bring along?
- How is the available capacity shared among the users?

LARGER STOCHASTIC NETWORKS...










Observe that we consider

Observe that we consider

Random dynamics on networks,

Observe that we consider

- Random dynamics on networks,
- but the structure of the network is random as well!

STOCHASTIC NETWORKS: COMMON FEATURES

 Multiple streams in network react to 'random fluctuations in outer world';

STOCHASTIC NETWORKS: COMMON FEATURES

- Multiple streams in network react to 'random fluctuations in outer world';
- this class of models can be applied in a wide variety of areas.



links are routers in, say, the Internet;

- links are routers in, say, the Internet;
- links can be 'up' and 'down', affecting specific classes of users;

- links are routers in, say, the Internet;
- links can be 'up' and 'down', affecting specific classes of users;
- external factors can spur increased activity across user classes.

- links are routers in, say, the Internet;
- links can be 'up' and 'down', affecting specific classes of users;
- external factors can spur increased activity across user classes.

Likewise: wireless communication network, with multiple classes of users reacting to fluctuations in channel conditions.

APPLICATION AREA 2: ROAD TRAFFIC NETWORK



APPLICATION AREA 2: ROAD TRAFFIC NETWORK

Ink failures could represent roadworks or accidents;

APPLICATION AREA 2: ROAD TRAFFIC NETWORK

- Ink failures could represent roadworks or accidents;
- external factors can spur increased activity across user classes (e.g. weather-related).

APPLICATION AREA 3: CHEMICAL REACTION NETWORK



APPLICATION AREA 3: CHEMICAL REACTION NETWORK

 \blacktriangleright customers \sim concentrations of different substances, that react with each other;

APPLICATION AREA 3: CHEMICAL REACTION NETWORK

- customers ~ concentrations of different substances, that react with each other;
- external factors may affect reaction speed (e.g. temperature-related).

100.13	+6.04	42.04		90.17	10	55,69	516,88	- 1	1735 1	13 IN 15 Dece	
34.18	-120	10.01	- 45	12,08	- 4	298.17	125.95	23	823	19 123	
150 QU	1.30	-4.57	87	8653		178.95	90,17	8	10.35 2000	55 A1	
100.01	-77.02	-3.72	114	1319		45216 405.00	12.08	72	9716	11 635 28 20 3	
387.32	+9.03	+3.96	98	1876	2	175.95	8653	98	898	12 559	
7254	+14.28	10 54	202	EU 33	6 100	20.32	1313	12	589 8	朝田道	
1	111.00	TC.DT	202	20.70	75	3379	15:51	19	323 5	285 283	
69.527	-11.32	-2.13			8	34.18	98.79	19	9813 9	15 EB	
upe no	LOUE	+1.96	15	8,43	15	458.04	5.07	27	88 6	14 203 15 76 1	
401.76	T0.10	1.00	54	376	19	387.32	32.87	78	2/0 0	08 195	
215,68	+8.35	+3.32	C1	CE 12	7	673.54	¥7.95	d1	10.4	13 525	
C10.00	10.00	+1.03	- 39	60.IC		552.09	1329	10	10	58 155	
158.92	+6.60	745	54	17.6		401.76	45.96	8	9879 15	12 22	
91000	-13.84	-5.15	63	15.31	6	215.68	389	10	5813	28 50	
10 million 1 f 1 f							- 1 1			and the second	

prices of correlated economic assets randomly fluctuate;

- prices of correlated economic assets randomly fluctuate;
- and do so by reacting to the same 'outer world' (i.e., state of the economy);

- prices of correlated economic assets randomly fluctuate;
- and do so by reacting to the same 'outer world' (i.e., state of the economy);
- (but in this case one rather uses continuous state-space stochastic process, rather than discrete state-space — e.g. stochastic differential equations.)

GENERIC FRAMEWORK: NETWORK OF QUEUES, OPERATING UNDER MARKOV MODULATION

 particles ('customers' in queueing lingo) move through a network;

GENERIC FRAMEWORK: NETWORK OF QUEUES, OPERATING UNDER MARKOV MODULATION

- particles ('customers' in queueing lingo) move through a network;
- arrival rates and service rates are affected by an external process ('background process');

GENERIC FRAMEWORK: NETWORK OF QUEUES, OPERATING UNDER MARKOV MODULATION

- particles ('customers' in queueing lingo) move through a network;
- arrival rates and service rates are affected by an external process ('background process');
- queues are 'coupled' because they react to common background process.

QUEUEING NETWORK







Framework is *rich*; covers also failure/repair system.

Framework is *rich*; covers also failure/repair system.

Background process corresponds to which links are 'up'/'down'.

Framework is *rich*; covers also failure/repair system.

Background process corresponds to which links are 'up'/'down'.

When link is down, all classes using this link have arrival rate 0 and departure rate $\infty.$






Notoriously hard...

- Notoriously hard...
- ➤ Simplest model: two single-server queues, modulated by the same background process X(t), irreducible continuous-time Markov chain, living on {1,..., d}.

- Notoriously hard...
- Simplest model: two single-server queues, modulated by the same background process X(t), irreducible continuous-time Markov chain, living on {1,..., d}.
 - If X(t) = i, then
 - arrival rate of queue A is λ_i^A (\rightarrow number of customers at queue A increases by 1), and of queue B it is λ_i^B (\rightarrow number of customers at queue B increases by 1).
 - departure rate of queue A is μ_i^A (\rightarrow number of customers at queue A decreases by 1), and of queue B it is μ_i^B (\rightarrow number of customers at queue B decreases by 1).

- Notoriously hard...
- Simplest model: two single-server queues, modulated by the same background process X(t), irreducible continuous-time Markov chain, living on {1,..., d}.
 - If X(t) = i, then
 - arrival rate of queue A is λ_i^A (\rightarrow number of customers at queue A increases by 1), and of queue B it is λ_i^B (\rightarrow number of customers at queue B increases by 1).
 - departure rate of queue A is μ_i^A (\rightarrow number of customers at queue A decreases by 1), and of queue B it is μ_i^B (\rightarrow number of customers at queue B decreases by 1).

Goal: joint distribution of stationary number in both queues:

$$\mathbb{P}(M^{\mathsf{A}}=k,M^{\mathsf{B}}=\ell).$$

Ironically:

marginals $\mathbb{P}(M^A = k)$ and $\mathbb{P}(M^B = \ell)$ can be found by elementary methods ('matrix-geometric form' — Neuts, early 1980s).

Ironically:

marginals $\mathbb{P}(M^A = k)$ and $\mathbb{P}(M^B = \ell)$ can be found by elementary methods ('matrix-geometric form' — Neuts, early 1980s).

Joint distribution has not been found (apart from trivial cases).

Problem: discontinuity at 0 (as queue cannot become negative). Solution requires solving non-trivial boundary value problem, unless one queue systematically majorizes the other.

MARKOV-MODULATED INFINITE-SERVER NETWORK

When assuming *infinitely many* servers, analysis is possible.

MARKOV-MODULATED INFINITE-SERVER NETWORK

When assuming *infinitely many* servers, analysis *is* possible.

Infinite-server queue is useful proxy for model with many servers (channels in wireless network, call center, segment of a road, generation and decay of mRNA in cells, etc.).

First: single infinite-server queue, in non-modulated setting.

First: single infinite-server queue, in non-modulated setting. M(t) is number of customers at time t; lives on $\{0, 1, 2...\}$.

First: single infinite-server queue, in non-modulated setting. M(t) is number of customers at time t; lives on $\{0, 1, 2...\}$.

- Rate up (from *i* to i + 1) is λ ,
- rate down (from *i* to i 1) is $i \mu$.

First: single infinite-server queue, in non-modulated setting. M(t) is number of customers at time t; lives on $\{0, 1, 2...\}$.

- Rate up (from *i* to i + 1) is λ ,
- rate down (from *i* to i 1) is $i \mu$.

Fairly complete analysis is possible: steady-state, transient, various performance metrics, etc.

Now impose *Markov modulation*. As before, X(t) is background process.

• $(X(t))_{t\geq 0}$: irreducible, Markov process on $\{1, \ldots, d\}$.

Now impose *Markov modulation*. As before, X(t) is background process.

- $(X(t))_{t \ge 0}$: irreducible, Markov process on $\{1, \ldots, d\}$.
- Transition rates: Q = (q_{ij})^d_{i,j=1}, (unique) invariant distribution: π.

Now impose *Markov modulation*. As before, X(t) is background process.

- $(X(t))_{t \ge 0}$: irreducible, Markov process on $\{1, \ldots, d\}$.
- Transition rates: Q = (q_{ij})^d_{i,j=1}, (unique) invariant distribution: π.

Let λ and μ be non-negative *d*-dimensional vectors.

Now impose *Markov modulation*. As before, X(t) is background process.

- $(X(t))_{t \ge 0}$: irreducible, Markov process on $\{1, \ldots, d\}$.
- Transition rates: Q = (q_{ij})^d_{i,j=1}, (unique) invariant distribution: π.

Let λ and μ be non-negative *d*-dimensional vectors.

M(t) lives on $\{0, 1, 2...\}$.

Now impose *Markov modulation*. As before, X(t) is background process.

- $(X(t))_{t \ge 0}$: irreducible, Markov process on $\{1, \ldots, d\}$.
- Transition rates: Q = (q_{ij})^d_{i,j=1}, (unique) invariant distribution: π.

Let λ and μ be non-negative *d*-dimensional vectors.

M(t) lives on $\{0, 1, 2...\}$.

- Rate up (from *i* to i + 1) is $\lambda_{X(t)}$,
- rate down (from *i* to i 1) is $i \mu_{X(t)}$.

Relatively small number of papers available (< 30...).

Relatively small number of papers available (< 30...).

Remarkably sharp distinction:

- Markov-modulated single-server queues: single queue easy, multiple queues hard (if not impossible);
- Markov-modulated infinite-server queues: partial results on single queue, but whatever can be done for single queue can be done for multiple queues as well.

Even in single queue, no explicit expression for distribution of stationary number of customers M...

Even in single queue, no explicit expression for distribution of stationary number of customers M...

Available results for Markov-modulated infinite-server (MMIS) queue typically in terms of

- ► d-dimensional system of (partial) differential equations to describe pgf of M(t) and stationary counterpart, M.
- Recursive scheme to determine all moments; for transient moments in all steps non-homogeneous system of linear differential equations needs to be solved.

Even in single queue, no explicit expression for distribution of stationary number of customers M...

Available results for Markov-modulated infinite-server (MMIS) queue typically in terms of

- ► d-dimensional system of (partial) differential equations to describe pgf of M(t) and stationary counterpart, M.
- Recursive scheme to determine all moments; for transient moments in all steps non-homogeneous system of linear differential equations needs to be solved.

See papers (between \pm 1990 and \pm 2005) by O'Cinneide/Purdue, Keilson/Servi, Adan/Fralix, D'Auria, ...

For Markov-modulated single-server queue a lot is known (Neuts): stationary number in the system follows a *matrix-geometric* distribution (generalization of M/M/1).

For Markov-modulated single-server queue a lot is known (Neuts): stationary number in the system follows a *matrix-geometric* distribution (generalization of M/M/1).

Therefore in the context of MMIS queue one would naïvely expect a matrix-Poisson distribution (generalization of $M/M/\infty)...$

For Markov-modulated single-server queue a lot is known (Neuts): stationary number in the system follows a *matrix-geometric* distribution (generalization of M/M/1).

Therefore in the context of MMIS queue one would naïvely expect a matrix-Poisson distribution (generalization of $M/M/\infty)...$

but this is not true.

MMIS queue comes in two flavors.

In above model (referred to as Model I) the transition rates depend on the current state of the background process. M(t) has Poisson distribution with random parameter

$$\int_0^t \lambda_{X(s)} e^{-\int_s^t \mu_{X(r)} \,\mathrm{d}r} \mathrm{d}s.$$

MMIS queue comes in two flavors.

In above model (referred to as Model I) the transition rates depend on the current state of the background process. M(t) has Poisson distribution with random parameter

$$\int_0^t \lambda_{X(s)} e^{-\int_s^t \mu_{X(r)} \,\mathrm{d}r} \mathrm{d}s.$$

Alternative model (Model II): service times are sampled upon arrival. M(t) has Poisson distribution with random parameter

$$\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

MMIS queue comes in two flavors.

In above model (referred to as Model I) the transition rates depend on the current state of the background process. M(t) has Poisson distribution with random parameter

$$\int_0^t \lambda_{X(s)} e^{-\int_s^t \mu_{X(r)} \,\mathrm{d}r} \mathrm{d}s.$$

Alternative model (Model II): service times are sampled upon arrival. M(t) has Poisson distribution with random parameter

$$\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

In this talk: μ_i identical across *i*, so that both models coincide.

First characterize invariant distribution $(\mathbf{p}_k)_{k=0}^{\infty}$, where \mathbf{p}_k is *d*-dimensional row-vector, defined by

$$[\boldsymbol{p}_k]_j := \mathbb{P}(M = k, X = j).$$

The (row-vector-)pgf $\boldsymbol{p}(z)$ is then given by

$$\boldsymbol{p}(z) := \sum_{k=0}^{\infty} \boldsymbol{p}_k z^k.$$

First characterize invariant distribution $(\mathbf{p}_k)_{k=0}^{\infty}$, where \mathbf{p}_k is *d*-dimensional row-vector, defined by

$$[\boldsymbol{p}_k]_j := \mathbb{P}(M = k, X = j).$$

The (row-vector-)pgf $\boldsymbol{p}(z)$ is then given by

$$\boldsymbol{p}(z) := \sum_{k=0}^{\infty} \boldsymbol{p}_k z^k.$$

Elementary (from Kolmogorov equations): p(z) satisfies ODE

$$\boldsymbol{p}(z)Q = (z-1)\left(\boldsymbol{p}'(z)\mathrm{diag}\{\boldsymbol{\mu}\} - \boldsymbol{p}(z)\mathrm{diag}\{\boldsymbol{\lambda}\}\right).$$

For transient behavior we obtain similar DE (which is a PDE).

With ODE

$$oldsymbol{
ho}(z) Q = (z-1) \left(oldsymbol{
ho}'(z) ext{diag}\{oldsymbol{\mu}\} - oldsymbol{
ho}(z) ext{diag}\{oldsymbol{\lambda}\}
ight).$$

stationary (factorial) moments can be found by differentiation and plugging in $z \uparrow 1$.

With ODE

$$\boldsymbol{p}(z)Q = (z-1) \left(\boldsymbol{p}'(z) \operatorname{diag} \{ \boldsymbol{\mu} \} - \boldsymbol{p}(z) \operatorname{diag} \{ \boldsymbol{\lambda} \} \right).$$

stationary (factorial) moments can be found by differentiation and plugging in $z \uparrow 1$.

Define

$$\boldsymbol{m}_k := \mathbb{E}[M(M-1)\cdots(M-k+1)\mathbf{1}_{\{X=i\}}] = \boldsymbol{p}^{(k)}(1).$$

Recursion (realize $m_0 = \pi$):

$$\boldsymbol{m}_k \boldsymbol{Q} = k \boldsymbol{m}_k \operatorname{diag} \{ \boldsymbol{\mu} \} - k \boldsymbol{m}_{k-1} \operatorname{diag} \{ \boldsymbol{\lambda} \}.$$

With ODE

$$\boldsymbol{p}(z)Q = (z-1) \left(\boldsymbol{p}'(z) \mathrm{diag}\{ \boldsymbol{\mu} \} - \boldsymbol{p}(z) \mathrm{diag}\{ \boldsymbol{\lambda} \} \right).$$

stationary (factorial) moments can be found by differentiation and plugging in $z \uparrow 1$.

Define

$$\boldsymbol{m}_k := \mathbb{E}[M(M-1)\cdots(M-k+1)\mathbf{1}_{\{X=i\}}] = \boldsymbol{p}^{(k)}(1).$$

Recursion (realize $m_0 = \pi$):

$$\boldsymbol{m}_k \boldsymbol{Q} = k \boldsymbol{m}_k \operatorname{diag} \{ \boldsymbol{\mu} \} - k \boldsymbol{m}_{k-1} \operatorname{diag} \{ \boldsymbol{\lambda} \}.$$

(Same for transient moments: then in each step of the recursion non-homogeneous system of differential equations must be solved.)

This is nice – one could numerically analyze the model now. However, we'd like to have 'structural insight' into the model...

This is nice – one could numerically analyze the model now. However, we'd like to have 'structural insight' into the model...

Therefore: consider *scaling limits*.

This is nice – one could numerically analyze the model now. However, we'd like to have 'structural insight' into the model...

Therefore: consider *scaling limits*.

We let some of the parameters of the model (viz. λ , μ , and Q) grow large of small, in a 'coordinated manner', and see whether we obtain any explicit results...
MMIS: SCALING LIMITS...

'Black magic': what is the right scaling? To provide intuition, let's explicitly compute the mean and variance of M(t).

Straightforward (for instance from Poisson-with-random-mean representation):

$$\mathbb{E}M(t) = \sum_{i=1}^d \pi_i \frac{\lambda_i}{\mu} (1 - e^{-\mu t}).$$

Straightforward (for instance from Poisson-with-random-mean representation):

$$\mathbb{E}M(t) = \sum_{i=1}^d \pi_i \frac{\lambda_i}{\mu} (1 - e^{-\mu t}).$$

Scaling the λ_i s by N blows up scale of process by a factor N...

Variance can be computed with law of total variance:

 $\operatorname{Var} M(t) = \mathbb{E}(\operatorname{Var}(M(t) | X)) + \operatorname{Var}(\mathbb{E}(M(t) | X)),$

with $X \equiv (X(s))_{s \in [0,t]}$.

Variance can be computed with law of total variance:

 $\mathbb{V}ar M(t) = \mathbb{E}(\mathbb{V}ar(M(t) | X)) + \mathbb{V}ar(\mathbb{E}(M(t) | X)),$ with $X \equiv (X(s))_{s \in [0,t]}.$

Clearly,

$$\mathbb{E}(\mathbb{V}\mathrm{ar}(M(t) \mid X)) = \mathbb{E}M(t) = \sum_{i=1}^{d} \pi_i \frac{\lambda_i}{\mu} (1 - e^{-\mu t}).$$

$$\begin{aligned} \operatorname{\mathbb{V}ar}(\mathbb{E}(M(t) \mid X)) &= \operatorname{\mathbb{V}ar}\left(\int_0^t \lambda_{X(s)} e^{-\mu(t-s)} \mathrm{d}s\right) \\ &= \int_0^t \int_0^t \operatorname{\mathbb{C}ov}\left(\lambda_{X(s)} e^{-\mu(t-s)}, \lambda_{X(u)} e^{-\mu(t-u)}\right) \mathrm{d}s \mathrm{d}u \\ &= \sum_{i,j=1}^d \lambda_i \lambda_j \int_0^t \int_0^t e^{-\mu(t-s)} e^{-\mu(t-u)} \operatorname{\mathbb{C}ov}\left(\mathbf{1}_{\{X(s)=i\}}, \mathbf{1}_{\{X(u)=j\}}\right) \mathrm{d}s \mathrm{d}u. \end{aligned}$$

$$\begin{aligned} \operatorname{\mathbb{V}ar}(\mathbb{E}(M(t) \mid X)) &= \operatorname{\mathbb{V}ar}\left(\int_0^t \lambda_{X(s)} e^{-\mu(t-s)} \mathrm{d}s\right) \\ &= \int_0^t \int_0^t \operatorname{\mathbb{C}ov}\left(\lambda_{X(s)} e^{-\mu(t-s)}, \lambda_{X(u)} e^{-\mu(t-u)}\right) \mathrm{d}s \mathrm{d}u \\ &= \sum_{i,j=1}^d \lambda_i \lambda_j \int_0^t \int_0^t e^{-\mu(t-s)} e^{-\mu(t-u)} \operatorname{\mathbb{C}ov}\left(\mathbf{1}_{\{X(s)=i\}}, \mathbf{1}_{\{X(u)=j\}}\right) \mathrm{d}s \mathrm{d}u. \end{aligned}$$

Reduces to:

$$\sum_{i,j=1}^{d} \lambda_i \lambda_j \int_0^t \int_0^u e^{-\mu(t-s)} e^{-\mu(t-u)} \pi_i (p_{ij}(u-s) - \pi_j) \mathrm{d}s \mathrm{d}u \\ + \sum_{i,j=1}^d \lambda_i \lambda_j \int_0^t \int_u^t e^{-\mu(t-s)} e^{-\mu(t-u)} \pi_i (p_{ij}(u-s) - \pi_j) \mathrm{d}s \mathrm{d}u.$$

Deviation matrix:

$$D_{ij} := \int_0^\infty (p_{ij}(t) - \pi_j) \mathrm{d}t.$$

Deviation matrix:

$$D_{ij} := \int_0^\infty (p_{ij}(t) - \pi_j) \mathrm{d}t.$$

Perform parameter scaling $\lambda \mapsto \lambda N$, and $Q \mapsto QN^{f}$, for some f > 0.

Deviation matrix:

$$D_{ij} := \int_0^\infty (p_{ij}(t) - \pi_j) \mathrm{d}t.$$

Perform parameter scaling $\lambda \mapsto \lambda N$, and $Q \mapsto QN^{f}$, for some f > 0.

Elementary calculations for stationary number in system:

$$\mathbb{V}\mathrm{ar} \mathcal{M}^{(N)} \sim \mathcal{N} \frac{\lambda_{\infty}}{\mu} + \mathcal{N}^{2-f} \sum_{i,j=1}^{d} \pi_i \frac{\lambda_i \lambda_j}{\mu} D_{ij},$$

with $\lambda_{\infty} := \sum_{i=1}^{d} \pi_i \lambda_i$.

Interesting dichotomy:

Interesting dichotomy:

▶ If *f* > 1 the variance essentially equals

$$\mathbb{V}\mathrm{ar}\: {\it M}^{({\it N})}\sim {\it N}arrho,$$
 where $arrho:=rac{\lambda_\infty}{\mu}.$

The system behaves 'Poissonian': background process moves faster than arrival process.

Limiting system is effectively a *non-modulated* infinite-server queue.

Interesting dichotomy:

▶ If *f* > 1 the variance essentially equals

$$\mathbb{V}\mathrm{ar}\, \mathit{M}^{(\mathit{N})}\sim \mathit{N}arrho,$$
 where $arrho:=rac{\lambda_{\infty}}{\mu}.$

The system behaves 'Poissonian': background process moves faster than arrival process.

Limiting system is effectively a *non-modulated* infinite-server queue.

▶ If *f* < 1 the variance essentially equals

$$\mathbb{V}\mathrm{ar} \, M^{(N)} \sim N^{2-f} \sum_{i,j=1}^d \pi_i \frac{\lambda_i \lambda_j}{\mu} D_{ij}.$$

'Local equilibria'.

We consider two types of limit results:

We consider two types of limit results:

▶ Behavior 'around the mean': central limit theorems. Crucially different behavior for f < 1, f = 1, and f > 1: apparently the right CLT scaling is N^γ, with

$$\gamma := \max\left\{rac{1}{2}, 1-rac{f}{2}
ight\}.$$

We consider two types of limit results:

▶ Behavior 'around the mean': central limit theorems. Crucially different behavior for f < 1, f = 1, and f > 1: apparently the right CLT scaling is N^γ, with

$$\gamma := \max\left\{\frac{1}{2}, 1 - \frac{f}{2}\right\}.$$

Rare-event behavior, 'far away from the mean': *large deviations*.
 Again crucially different behavior for f < 1, f = 1, and f > 1.

MMIS: COAUTHORS

- At University of Amsterdam: Peter Spreij and Gang Huang.
- At CWI: Joke Blom and Halldóra Þórsdottir.



MMIS: COAUTHORS

- At University of Melbourne: Peter Taylor.
- At Hebrew University: Offer Kella.
- At Supélec Paris: Koen de Turck.
- At University Ghent: *Marijn Jansen*.



REST OF THE TALK

- Central limit theorems,
- Large deviations (very brief, time permitting!).

REST OF THE TALK

- Central limit theorems,
- Large deviations (very brief, time permitting!).

For both I'll present the main ideas and underlying reasoning, state the result in its basic form. Many extensions, generalizations, and ramifications are possible.

Basic form: single MMIS queue, stationary behavior.

Basic form: single MMIS queue, stationary behavior.

• Set up a DE for the PGF of $M^{(N)}$.

Basic form: single MMIS queue, stationary behavior.

- Set up a DE for the PGF of $M^{(N)}$.
- Transform this is into a DE for the MGF of

$$ilde{M}^{(N)} := rac{M^{(N)} - N arrho}{N^{\gamma}}$$

Basic form: single MMIS queue, stationary behavior.

- Set up a DE for the PGF of $M^{(N)}$.
- Transform this is into a DE for the MGF of

$$ilde{M}^{(N)} := rac{M^{(N)} - N arrho}{N^{\gamma}}$$

• Manipulate this expression and let $N \to \infty$.

Basic form: single MMIS queue, stationary behavior.

- Set up a DE for the PGF of $M^{(N)}$.
- Transform this is into a DE for the MGF of

$$ilde{M}^{(N)} := rac{M^{(N)} - Narrho}{N^{\gamma}}$$

- Manipulate this expression and let $N \to \infty$.
- Observe that we obtain a Gaussian limit.

Basic form: single MMIS queue, stationary behavior.

- Set up a DE for the PGF of M^(N).
- Transform this is into a DE for the MGF of

$$ilde{M}^{(N)} := rac{M^{(N)} - N arrho}{N^{\gamma}}.$$

- Manipulate this expression and let $N \to \infty$.
- Observe that we obtain a Gaussian limit.

By now we have various alternative techniques (generator-based; martingale-based); this one is most insightful.

First characterize invariant distribution $(\boldsymbol{p}_{k}^{(N)})_{k=0}^{\infty}$, where $\boldsymbol{p}_{k}^{(N)}$ is *d*-dimensional row-vector, defined by

$$[\mathbf{p}_{k}^{(N)}]_{j} := \mathbb{P}(M^{(N)} = k, X^{(N)} = j).$$

The (row-vector-)pgf $\boldsymbol{p}^{(N)}(z)$ is then given by

$$\boldsymbol{\rho}^{(N)}(z) := \sum_{k=0}^{\infty} \boldsymbol{\rho}_k^{(N)} z^k.$$

First characterize invariant distribution $(\boldsymbol{p}_{k}^{(N)})_{k=0}^{\infty}$, where $\boldsymbol{p}_{k}^{(N)}$ is *d*-dimensional row-vector, defined by

$$[\mathbf{p}_{k}^{(N)}]_{j} := \mathbb{P}(M^{(N)} = k, X^{(N)} = j).$$

The (row-vector-)pgf $\boldsymbol{p}^{(N)}(z)$ is then given by

$$\boldsymbol{p}^{(N)}(z) := \sum_{k=0}^{\infty} \boldsymbol{p}_k^{(N)} z^k.$$

Kolmogorov equations are now given by

$$\boldsymbol{p}^{(N)}(z)Q = rac{(z-1)}{N^f}\left((\boldsymbol{p}^{(N)})'(z)\mathrm{diag}\{\boldsymbol{\mu}\} - N\boldsymbol{p}^{(N)}(z)\mathrm{diag}\{\boldsymbol{\lambda}\}\right).$$

Translate into mgf of $\tilde{M}^{(N)}$:

$$egin{aligned} & ilde{oldsymbol{p}}^{(N)}(artheta) &:= & \mathbb{E} e^{artheta} ilde{M}^{(N)} = & \mathbb{E} \exp\left(artheta rac{M^{(N)} - Narrho}{N^{\gamma}}
ight) \ &= & e^{-artheta N^{1-\gamma}arrho} oldsymbol{p}^{(N)} \left(e^{artheta N^{-\gamma}}
ight). \end{aligned}$$

Manipulate resulting DE.

Manipulate resulting DE.

 $\blacktriangleright \Pi := \mathbf{1} \pi^{\mathrm{T}}.$

Manipulate resulting DE.

- $\blacktriangleright \ \Pi := \mathbf{1} \pi^{\mathrm{T}}.$
- $F := D + \Pi$ (fundamental matrix).

Manipulate resulting DE.

- $\blacktriangleright \ \Pi := \mathbf{1} \pi^{\mathrm{T}}.$
- $F := D + \Pi$ (fundamental matrix).
- Standard properties: $QF = FQ = \Pi I$, $F\mathbf{1} = \mathbf{1}$, and $\Pi D = D\Pi = 0$.

Manipulate resulting DE.

- $\blacktriangleright \ \Pi := \mathbf{1} \pi^{\mathrm{T}}.$
- $F := D + \Pi$ (fundamental matrix).
- Standard properties: $QF = FQ = \Pi I$, $F\mathbf{1} = \mathbf{1}$, and $\Pi D = D\Pi = 0$.

Postmultiply DE by F.

When the dust has settled...

$$\begin{split} \tilde{\boldsymbol{p}}^{(N)}(\vartheta) &= \tilde{\boldsymbol{p}}^{(N)}(\vartheta) \Pi + N^{1-f} \left(z^{(N)}(\vartheta) - 1 \right) \tilde{\boldsymbol{p}}^{(N)}(\vartheta) \mathrm{diag}\{\lambda\} F \\ &- N^{1-f} \left(1 - \frac{1}{z^{(N)}(\vartheta)} \right) \varrho \, \tilde{\boldsymbol{p}}^{(N)}(\vartheta) \mathrm{diag}\{\mu\} F \\ &- N^{1-f-\beta/2} \left(1 - \frac{1}{z^{(N)}(\vartheta)} \right) (\tilde{\boldsymbol{p}}^{(N)})'(\vartheta) \mathrm{diag}\{\mu\} F. \end{split}$$

Here: $\beta := \min\{f, 1\}$, and $z \equiv z^{(N)}(\vartheta) := \exp(\vartheta N^{-1+\beta/2})$.

Then
CENTRAL LIMIT THEOREM, ctd.

Then

► 'Taylor' the z, and iterate the equation to get rid of all terms that are o(N^{-f}):

CENTRAL LIMIT THEOREM, ctd.

Then

- ► 'Taylor' the z, and iterate the equation to get rid of all terms that are o(N^{-f}):
- Goal: transform the coupled system of ODE's in *p̃*^(N)(*θ*) into a single-dimensional ODE in terms of φ^(N)(*θ*) := *p̃*^(N)(*θ*)1. Postmultiply by 1 N^f/*θ*; realize that Π1 = 1 and F1 = 1.

$$(\phi^{(N)})'(\vartheta) = \vartheta N^{\beta-f} \kappa \phi^{(N)}(\vartheta) + \vartheta N^{\beta-1} \varrho \phi^{(N)}(\vartheta) + o(1), \text{ with}$$

 $\kappa := rac{\pi^{\mathrm{T}}(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})F(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})\mathbf{1}}{\mu}.$

$$(\phi^{(N)})'(\vartheta) = \vartheta N^{\beta-f} \kappa \phi^{(N)}(\vartheta) + \vartheta N^{\beta-1} \varrho \phi^{(N)}(\vartheta) + o(1), \text{ with}$$

 $\kappa := rac{\pi^{\mathrm{T}}(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})F(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})\mathbf{1}}{\mu}.$

Conclude, recalling that $\beta = \min\{f, 1\}$,

• f < 1: only first term RHS matters \rightarrow Normal distribution with variance

$$\sum_{i,j=1}^d \pi_i \frac{\lambda_i \lambda_j}{\mu} D_{ij}.$$

$$(\phi^{(N)})'(\vartheta) = \vartheta N^{\beta-f} \kappa \phi^{(N)}(\vartheta) + \vartheta N^{\beta-1} \varrho \phi^{(N)}(\vartheta) + o(1), \text{ with}$$

 $\kappa := rac{\pi^{\mathrm{T}}(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})F(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})\mathbf{1}}{\mu}.$

Conclude, recalling that $\beta = \min\{f, 1\}$,

• f < 1: only first term RHS matters \rightarrow Normal distribution with variance

$$\sum_{i,j=1}^d \pi_i \frac{\lambda_i \lambda_j}{\mu} D_{ij}.$$

f > 1: only second term RHS matters → Normal distribution with variance

$$\sum_{i=1}^d \pi_i \frac{\lambda_i}{\mu} = \frac{\lambda_\infty}{\mu}$$

$$(\phi^{(N)})'(\vartheta) = \vartheta N^{\beta-f} \kappa \phi^{(N)}(\vartheta) + \vartheta N^{\beta-1} \varrho \phi^{(N)}(\vartheta) + o(1), \text{ with}$$

 $\kappa := rac{\pi^{\mathrm{T}}(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})F(\mathrm{diag}\{\lambda\} - \varrho \mathrm{diag}\{\mu\})\mathbf{1}}{\mu}.$

Conclude, recalling that $\beta = \min\{f, 1\}$,

• f < 1: only first term RHS matters \rightarrow Normal distribution with variance

$$\sum_{i,j=1}^d \pi_i \frac{\lambda_i \lambda_j}{\mu} D_{ij}.$$

F > 1: only second term RHS matters → Normal distribution with variance

$$\sum_{i=1}^{d} \pi_i \frac{\lambda_i}{\mu} = \frac{\lambda_{\infty}}{\mu}$$

• f = 1: both terms matter.

LARGE DEVIATIONS

Under the same scaling, large deviations can be examined. Objective in transient case:

$$\lim_{N o \infty} rac{1}{N} \log \mathbb{P}\left(rac{M^{(N)}(t)}{N} \geq a
ight);$$

for stationary case, replace $M^{(N)}(t)$ by $M^{(N)}$.

Again crucially different behavior for f > 1 and f < 1.

First concentrate on f > 1.

First concentrate on f > 1.

 Stationary case: rate function looks like that of Poisson random variable with parameter

$$\varrho := \frac{\lambda_{\infty}}{\mu}.$$

First concentrate on f > 1.

 Stationary case: rate function looks like that of Poisson random variable with parameter

$$\varrho := \frac{\lambda_{\infty}}{\mu}.$$

> Transient case: same result, but then with parameter

$$\varrho_t := \frac{\lambda_\infty}{\mu} (1 - e^{-\mu t}).$$

Second regime: f < 1.

Take for ease f = 0 (that is, background process is unscaled) and Model II (for Model I analysis is similar). Recall: $M^{(N)}(t)$ has a Poisson distribution with parameter

$$N\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

Second regime: f < 1.

Take for ease f = 0 (that is, background process is unscaled) and Model II (for Model I analysis is similar). Recall: $M^{(N)}(t)$ has a Poisson distribution with parameter

$$N\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

A single path f(s) of X(s) ($s \in [0, t]$) determines asymptotics.

Second regime: f < 1.

Take for ease f = 0 (that is, background process is unscaled) and Model II (for Model I analysis is similar). Recall: $M^{(N)}(t)$ has a Poisson distribution with parameter

$$N\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

- A single path f(s) of X(s) ($s \in [0, t]$) determines asymptotics.
- Naïve first thought: background process (essentially) stays in state *i* that maximizes λ_i/μ_i.

Second regime: f < 1.

Take for ease f = 0 (that is, background process is unscaled) and Model II (for Model I analysis is similar). Recall: $M^{(N)}(t)$ has a Poisson distribution with parameter

$$N\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

- A single path f(s) of X(s) ($s \in [0, t]$) determines asymptotics.
- Naïve first thought: background process (essentially) stays in state *i* that maximizes λ_i/μ_i.
 Wrong! Result: X(s) close to path f*(s), defined by

$$\arg\max_{f(s)}\lambda_{f(s)}e^{-\mu_{f(s)}(t-s)}.$$

Idea: maximize parameter of Poisson distribution.

Second regime: f < 1.

Take for ease f = 0 (that is, background process is unscaled) and Model II (for Model I analysis is similar). Recall: $M^{(N)}(t)$ has a Poisson distribution with parameter

$$N\int_0^t \lambda_{X(s)} e^{-\mu_{X(s)}(t-s)} \mathrm{d}s.$$

- A single path f(s) of X(s) ($s \in [0, t]$) determines asymptotics.
- Naïve first thought: background process (essentially) stays in state *i* that maximizes λ_i/μ_i.
 Wrong! Result: X(s) close to path f*(s), defined by

$$\arg\max_{f(s)}\lambda_{f(s)} e^{-\mu_{f(s)}(t-s)}.$$

Idea: maximize parameter of Poisson distribution.

Again, this was result in its basic form. Many extensions possible!

 Area of stochastic networks highly relevant, and mathematically extremely rich,

- Area of stochastic networks highly relevant, and mathematically extremely rich,
- with many challenges for the years to come,

- Area of stochastic networks highly relevant, and mathematically extremely rich,
- with many challenges for the years to come,
- particularly at the interface with algorithmics/combinatorics and statistics,

- Area of stochastic networks highly relevant, and mathematically extremely rich,
- with many challenges for the years to come,
- particularly at the interface with algorithmics/combinatorics and statistics,
- examples in talk illustrate how they complement each other.

- Area of stochastic networks highly relevant, and mathematically extremely rich,
- with many challenges for the years to come,
- particularly at the interface with algorithmics/combinatorics and statistics,
- examples in talk illustrate how they complement each other.

Thanks for your attention!