

# Smoothed Analysis of Algorithms

## Part II: Binary and Multiobjective Optimization

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## Outline

### 1 Binary Optimization Problems

When does a binary optimization problem have **polynomial smoothed complexity**?

### 2 Multiobjective Optimization

How many **Pareto-optimal solutions** do usually exist?

### 3 Conclusions

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## Linear Binary Optimization Problem

- **set of feasible solutions**  $\mathcal{S} \subseteq \{0, 1\}^n$   
solution  $x = (x_1, \dots, x_n) \in \mathcal{S}$  consists of  $n$  **binary variables**
- **linear objective function**  
$$\max c^T x = c_1 x_1 + \dots + c_n x_n$$

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$\mathcal{S}$  can encode **arbitrary combinatorial structure**, e.g., for a given graph, all **paths from  $s$  to  $t$** , all **Hamiltonian cycles**, all **spanning trees**, ...



- **Knapsack Problem**: variable  $x_i \in \{0, 1\}$  for each item  $i$   
$$\mathcal{S} = \{x \mid w_1 x_1 + \dots + w_n x_n \leq t\}$$



- **TSP**: variable  $x_e \in \{0, 1\}$  for each  $e \in E$   
$$\mathcal{S} = \{x \mid x \text{ encodes Hamiltonian cycle}\}$$

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$f_i: [-1, 1] \rightarrow [0, \phi]$  for every  $c_i$  and some  $\phi \geq 1$ .

Every  $c_i$  is **drawn independently** according to  $f_i$ .

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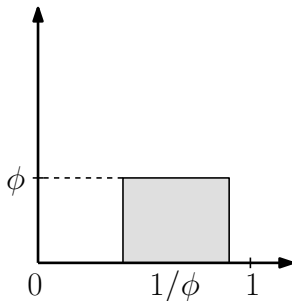
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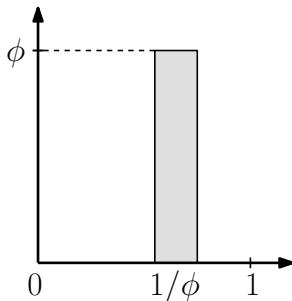
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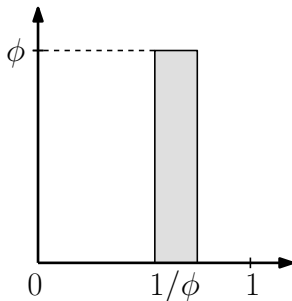
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- $\phi$  large  $\approx$  worst case  
   $\phi$  small  $\approx$  average case
- $\mathcal{S}$  is not perturbed!



Theorem [Beier, Vöcking (STOC 2004)]

linear binary opt. problem has polynomial smoothed complexity



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- **TSP:** strongly NP-hard (even if all edge lengths are 1 or 2)  
 $\Rightarrow$  no polynomial smoothed complexity

# Polynomial Smoothed Complexity

- $A$  = algorithm
- $\mathcal{I}_n$  = set of inputs of length  $n$
- $\text{per}_\phi(I)$  = perturbation of instance  $I$
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Algorithm  $A$  has polynomial smoothed complexity if there exist  $\alpha > 0$  and  $\beta > 0$  with

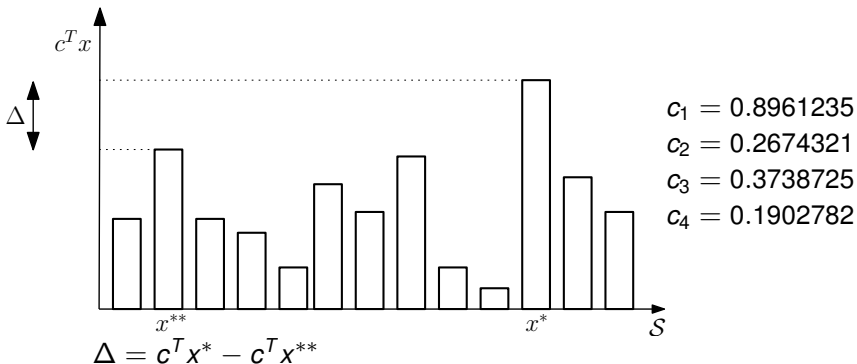
$$\max_{I \in \mathcal{I}_n} \mathbf{E}[T_A(\text{per}_\phi(I))^\alpha] \leq \beta n \phi.$$

# Winner Gap

**Idea:** Round coefficients  $c_j$  and apply pseudo-polyn. algo

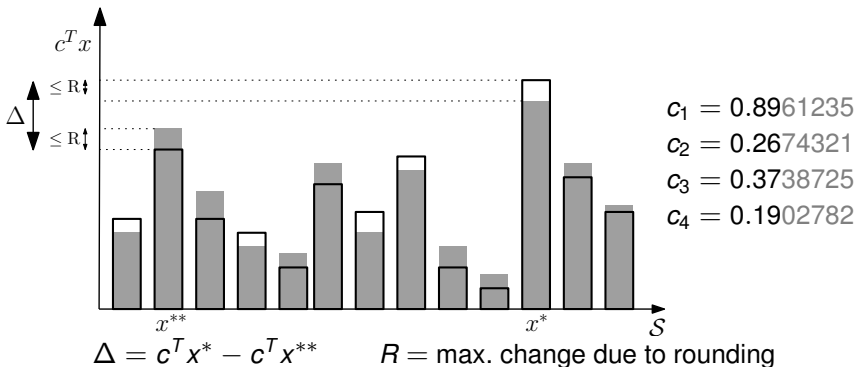
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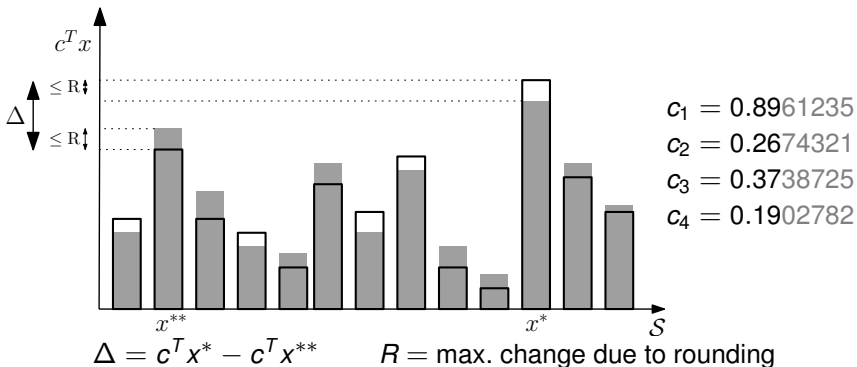


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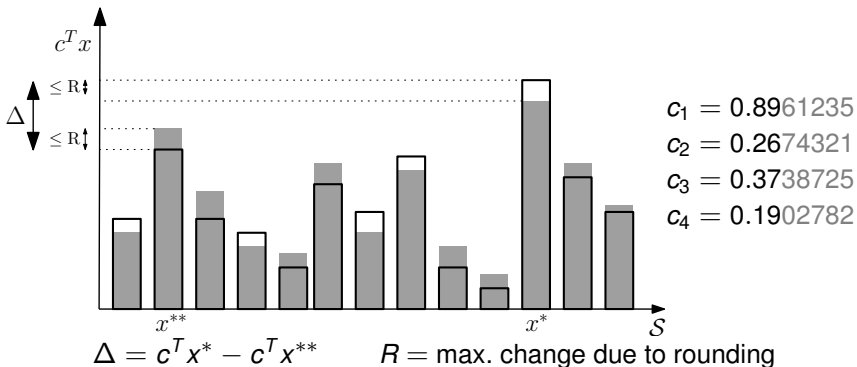


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- Rounding **after the  $b$ -th bit**  $\Rightarrow |c_j - [c_j]| \leq 2^{-b}$   
 $\Rightarrow \forall x \in S : |c^T x - [c]^T x| \leq n2^{-b} = R$

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- $\Delta > 2R \Rightarrow$  **rounding does not change optimal solution**

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For every  $p \in (0, 1]$  and  $b \geq \log\left(\frac{n^2\phi}{p}\right) + 2$ ,

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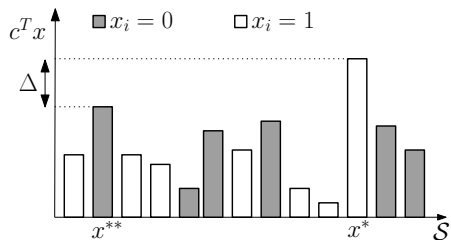
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- Round coefficients after a **logarithmic number of bits** and call pseudo-polynomial algorithm.
- If necessary, increase precision and repeat.

# Proof of Isolation Lemma

## Lemma

For  $\varepsilon \geq 0$ ,  $\Pr[\Delta < \varepsilon] \leq 2n\phi\varepsilon$ .

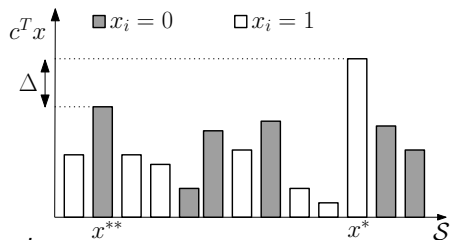


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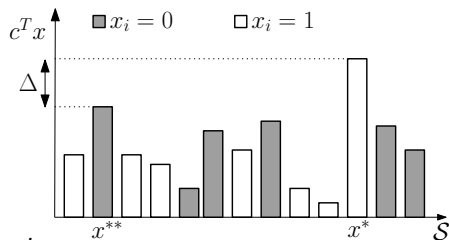


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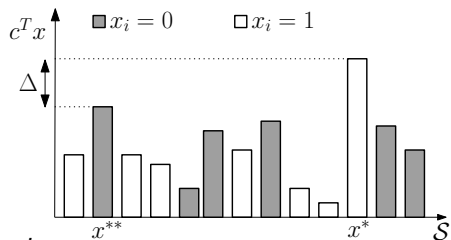
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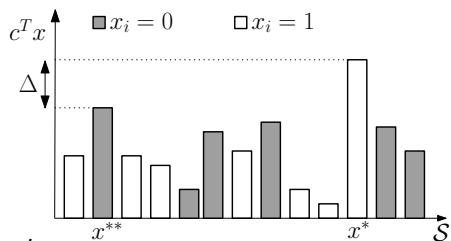


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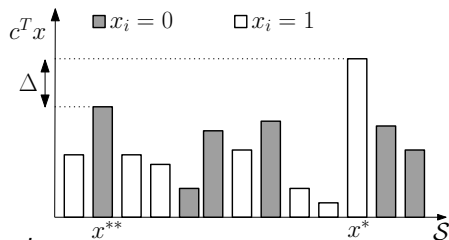
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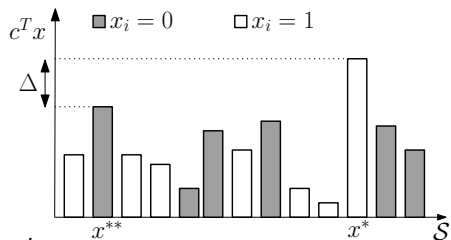


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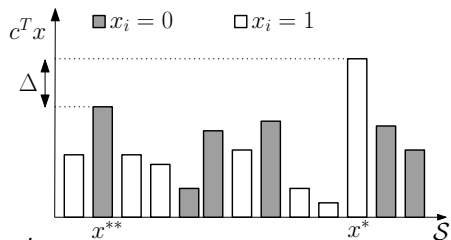


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- Union Bound over all  $n$  choices for  $i$ . □

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[Beier, Vöcking (STOC 2004)]

Theorem remains true if linear constraints are perturbed.

[R., Vöcking (IPCO 2005)]

Theorem remains true for integer optimization problems.

## Outline

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When does a binary optimization problem have **polynomial smoothed complexity**?

### ② Multiobjective Optimization

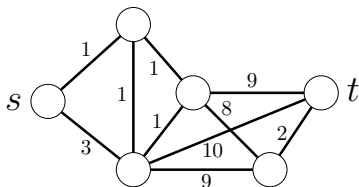
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### ③ Conclusions

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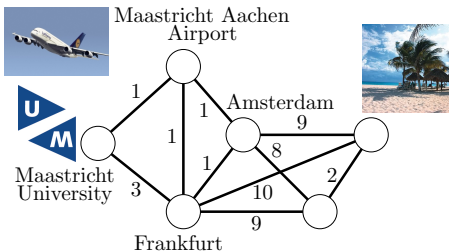


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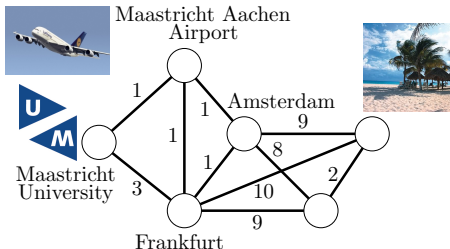


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**Multiobjective Opt. Problem:**  $\min f_1(x), \dots, \min f_d(x)$  s.t.  $x \in \mathcal{S}$ .  
Usually, there is **no solution that is simultaneously optimal for all  $f_i$** .

Question

What can we do algorithmically to **support the decision maker**?



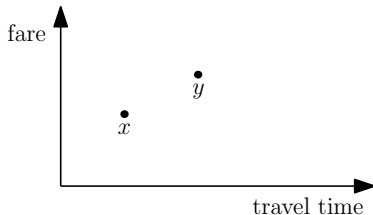
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$x \in \mathcal{S}$  **dominates**  $y \in \mathcal{S} \iff$

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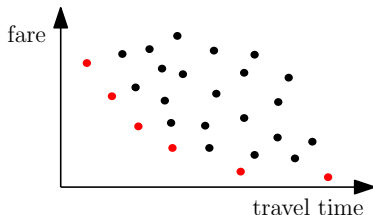
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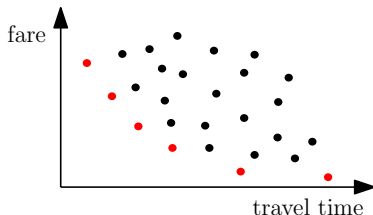
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Often the **Pareto curve** is generated:

- Pareto curve **limits options for decision maker**.
- **Monotone functions** are optimized by Pareto-optimal solutions, e.g.,  $\lambda_1 w^1(x) + \dots + \lambda_d w^d(x)$  or  $w^1(x) \cdot \dots \cdot w^d(x)$ .
- Tool for solving **single-criterion problems**

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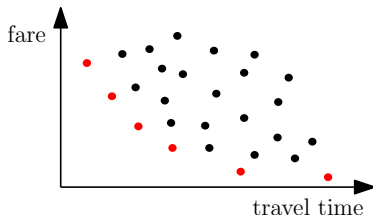
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Central Question

**How large** is the Pareto curve?

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solution  $x = (x_1, \dots, x_n) \in \mathcal{S}$  consists of  $n$  **binary variables**
- **$d$  linear objective functions:**  
 $\forall i \in \{1, \dots, d\}: \min w^i(x) = w_1^i x_1 + \dots + w_n^i x_n$

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## How large is the Pareto curve?

- **Exponential in the worst case** for almost all problems.
- In practice, **often few Pareto optimal solutions.**



**Example: Train Connections**  
w.r.t. travel time, fare, number of train changes  
[Müller-Hannemann, Weihe 2001]

# Results (Bicriteria Optimization)

**Adversary** chooses  $\mathcal{S}$  and a **probability density**

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extension to **integer optimization problems**

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$$P_d(n, \phi) = O(n^{2d} \phi^d) \quad P_d(n, \phi) = \Omega(n^{d-1.5} \phi^d)$$

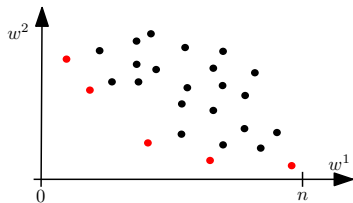
extension to non-linear objective functions

# Bicriteria Optimization

Beier, R., Vöcking (IPCO 2007)

- $\min w^1(x) = w_1x_1 + \dots + w_nx_n$  and  $\min w^2(x)$
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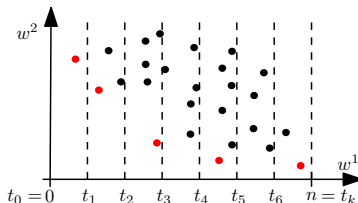
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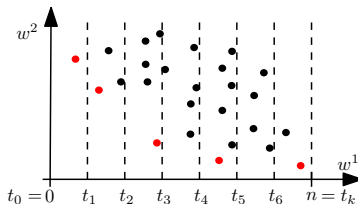
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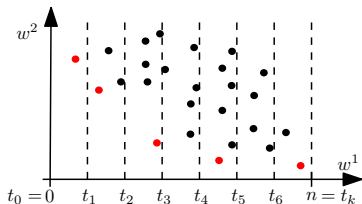
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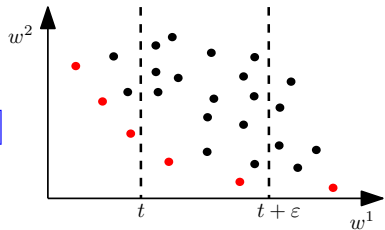
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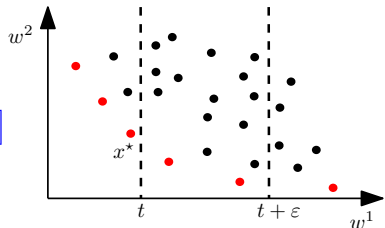


# Loser Gap

$$\Pr [\exists x \in \mathcal{P}: w^1(x) \in [t, t + \varepsilon]]$$



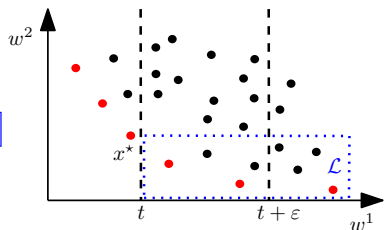
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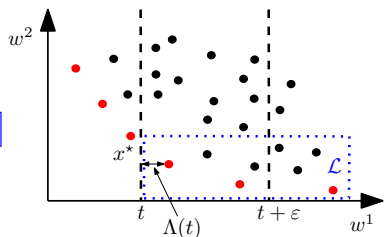
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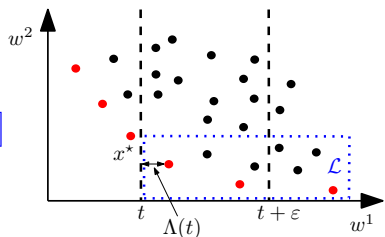
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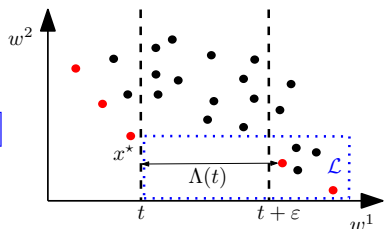
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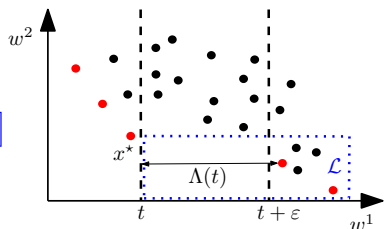
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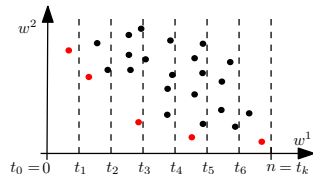
For every  $\varepsilon \geq 0$  and  $t \in \mathbb{R}$ ,  $\Pr[\Lambda(t) \leq \varepsilon] \leq n\phi\varepsilon$ .

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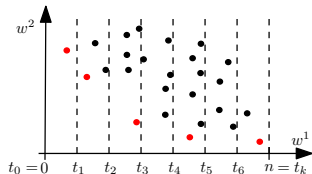


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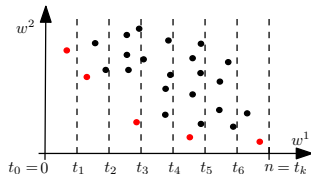
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□



Beier, R., Vöcking (IPCO 2007)

$$P_2(n, \phi) = O(n^2\phi)$$

## Outline

### 1 Binary Optimization Problems

When does a binary optimization problem have **polynomial smoothed complexity**?

### 2 Multiobjective Optimization

How many **Pareto-optimal solutions** do usually exist?

### 3 Conclusions

## Summary

Smoothed analysis is a promising framework for a more realistic theory of algorithms. It explains success of simplex algorithm, 2-Opt, and many other algorithms.

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## Open Questions

- analyze other pivot rules for simplex method
- improve exponents of smoothed running time for 2-Opt etc.
- analyze your favorite problem/ algo that is hard in the worst case
- use insights to develop better algorithms
- explore other frameworks for realistic theory